Probabilistic modeling natural way to treat data

Hussein Rappel

University of Luxembourg

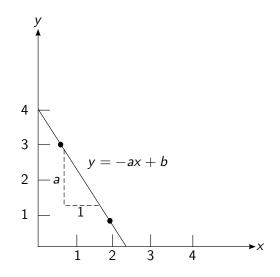
h.rappel@gmail.com

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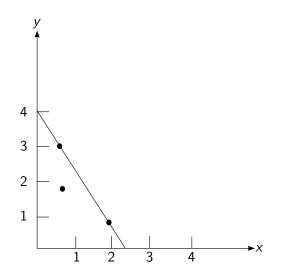


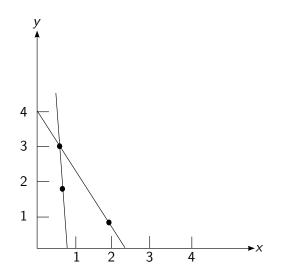


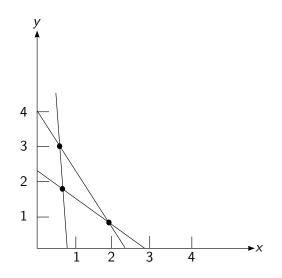
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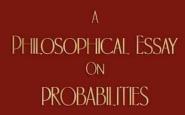


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PIERRE-SIMON LAPLACE



Each point can be written as the model+ a corruption:

$$y_1 = ax + c + \omega_1$$

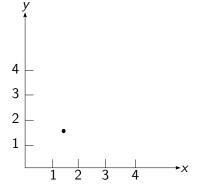
$$y_2 = ax + c + \omega_2$$

$$y_3 = ax + c + \omega_3$$

 ω is the difference between real world and model which can be presented by a probability distribution.

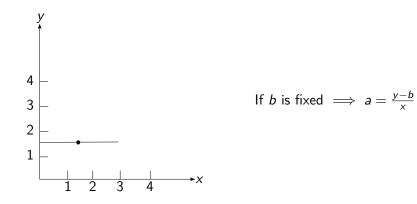
We call ω noise!

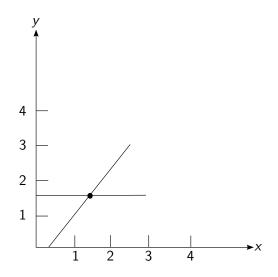
What if our observations are less than model parameters? Underdetermined system

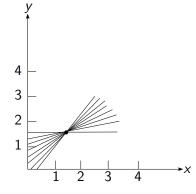


How can we fit the y = ax + b line, having only one point?

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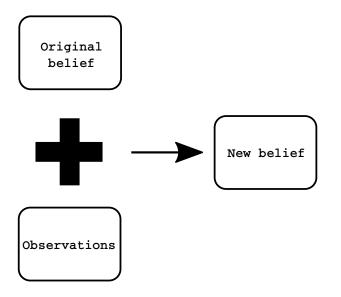




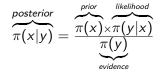
 $b \sim \pi_1 \implies a \sim \pi_2$

- This is called Bayesian treatment.
- The model parameters are treated as random variables.

Bayesian perspective



Bayesian formula (inverse probability)



 $\begin{array}{l} y := \text{observation} \\ x := \text{parameter} \\ \pi(x) := \text{original belief} \\ \pi(y|x) := \text{given by the mathematical model that relates } y \text{ to } x \\ \pi(y) := \text{ is a constant number} \end{array}$

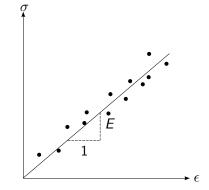
Bayesian formula (inverse probability)

$\pi(x|y) \propto \pi(x) imes \pi(y|x)$

BI in computational mechanics



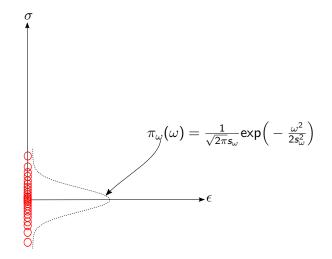




$$\sigma = E\epsilon$$

 $y = E\epsilon + \omega$ $\Omega \sim \pi_{\omega}(\omega)$

Capital letters denote a random variable



Noise PDF is modeled through calibration test.

Bayes' formula:

$$\pi(E|y) = rac{\pi(E)\pi(y|E)}{\pi(y)} = rac{\pi(E)\pi(y|E)}{k}$$

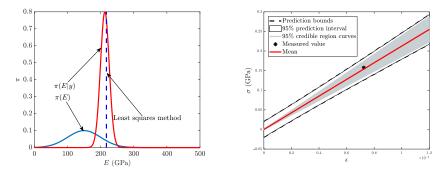
$$\pi(E|y) \propto \pi(E)\pi(y|E)$$

$$y = E\epsilon + \omega$$
$$\Omega \sim N(0, s_{\omega}^2)$$

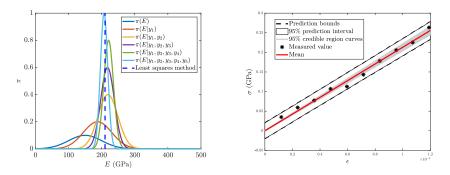
$$\pi(y|E) = \frac{1}{\sqrt{2\pi}s_{\omega}} \exp\left(-\frac{(y-E\epsilon)^2}{2s_{\omega}^2}\right)$$

Posterior:

$$\pi(E|y) \propto \exp\left(-rac{(E-\overline{E})^2}{2s_E^2}
ight) \exp\left(-rac{(y-E\epsilon)^2}{2s_\omega^2}
ight)$$

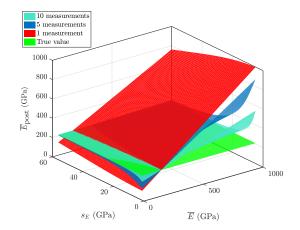


- Prediction interval: An estimate of an interval in which an observation will fall, with a certain probability.
- Credible region: A region of a distribution in which it is believed that a random variable lie with a certain probability.



 Increase in number of observations/measurements makes us more sure of identification result.

Prior effect



▶ Increase in number of observations/measurements decreases the effect of prior.

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- The same logic can be used to model other kinds of uncertainties/unknowns e.g. model uncertainties and material variability.
- In Bayesian paradigm our assumptions are clearly stated (e.g. the prior, model and ...).
- ► As the number of observation/measurements increases we become more sure of our identification results.

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Some references

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