



Computational Sciences Luxembourg

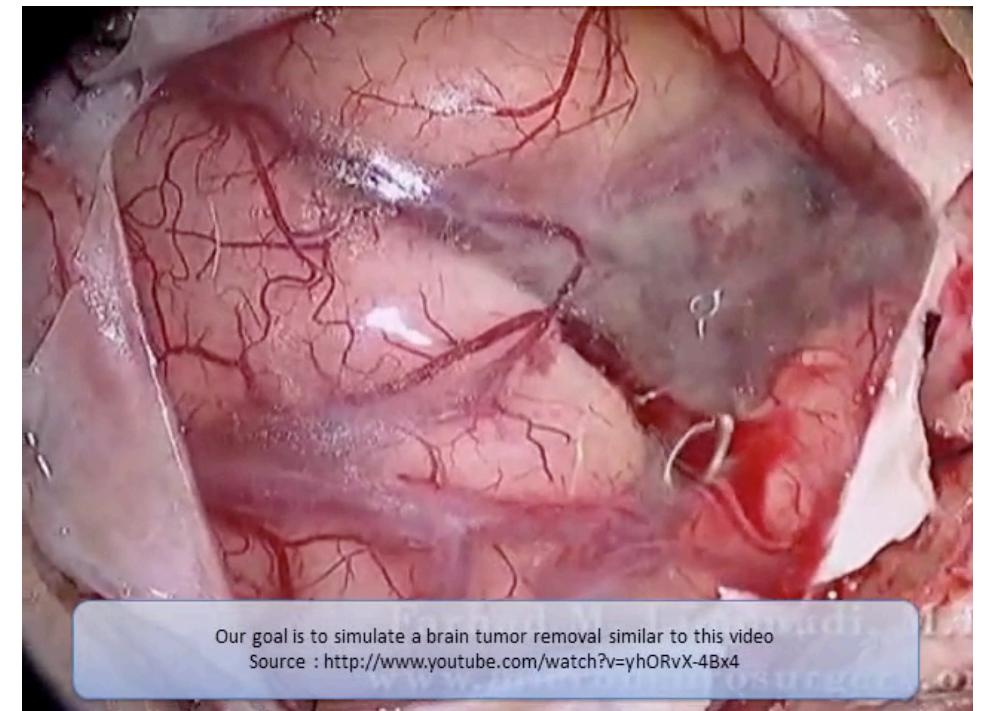
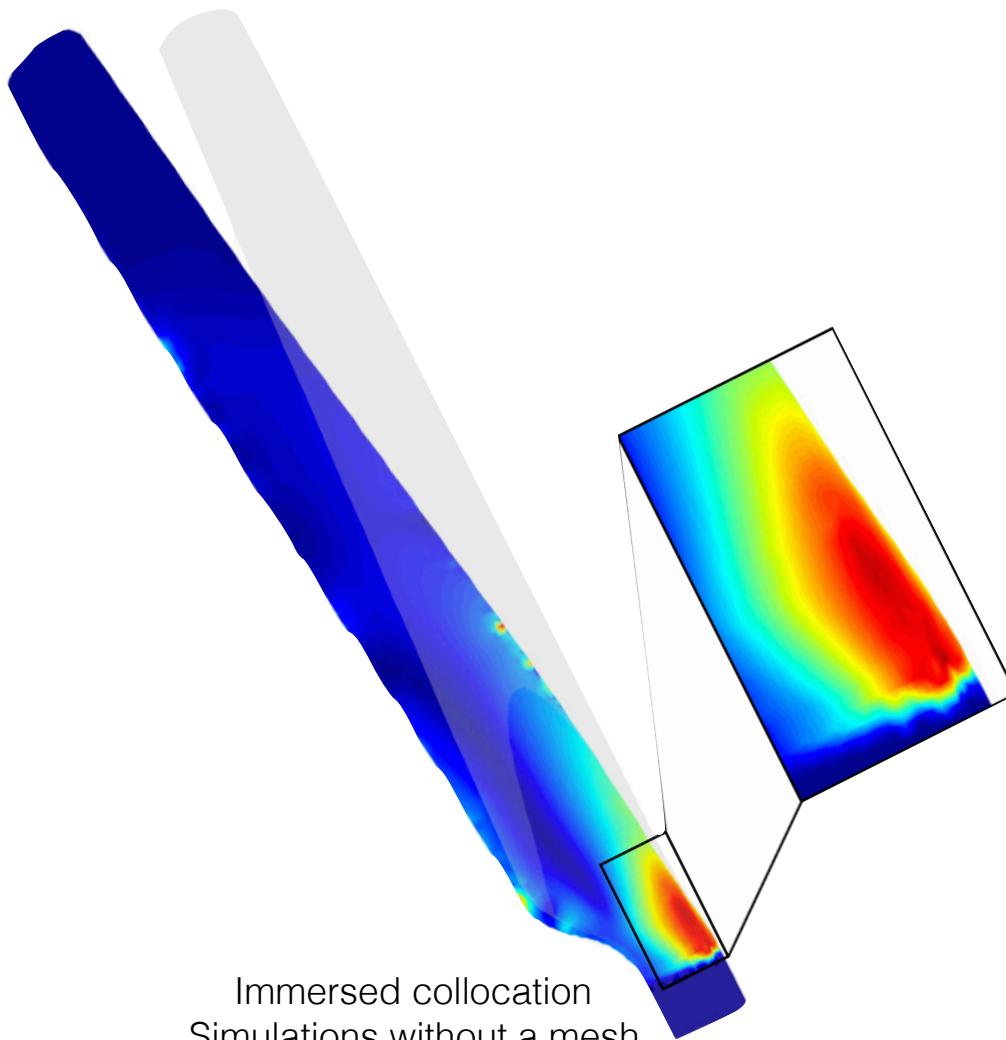


Computational Sciences and the Transition to Data-Driven Modelling and Simulation



Case studies in Engineering & Personalised Medicine





Real-time cutting, MEDIA2014, IEEE2017

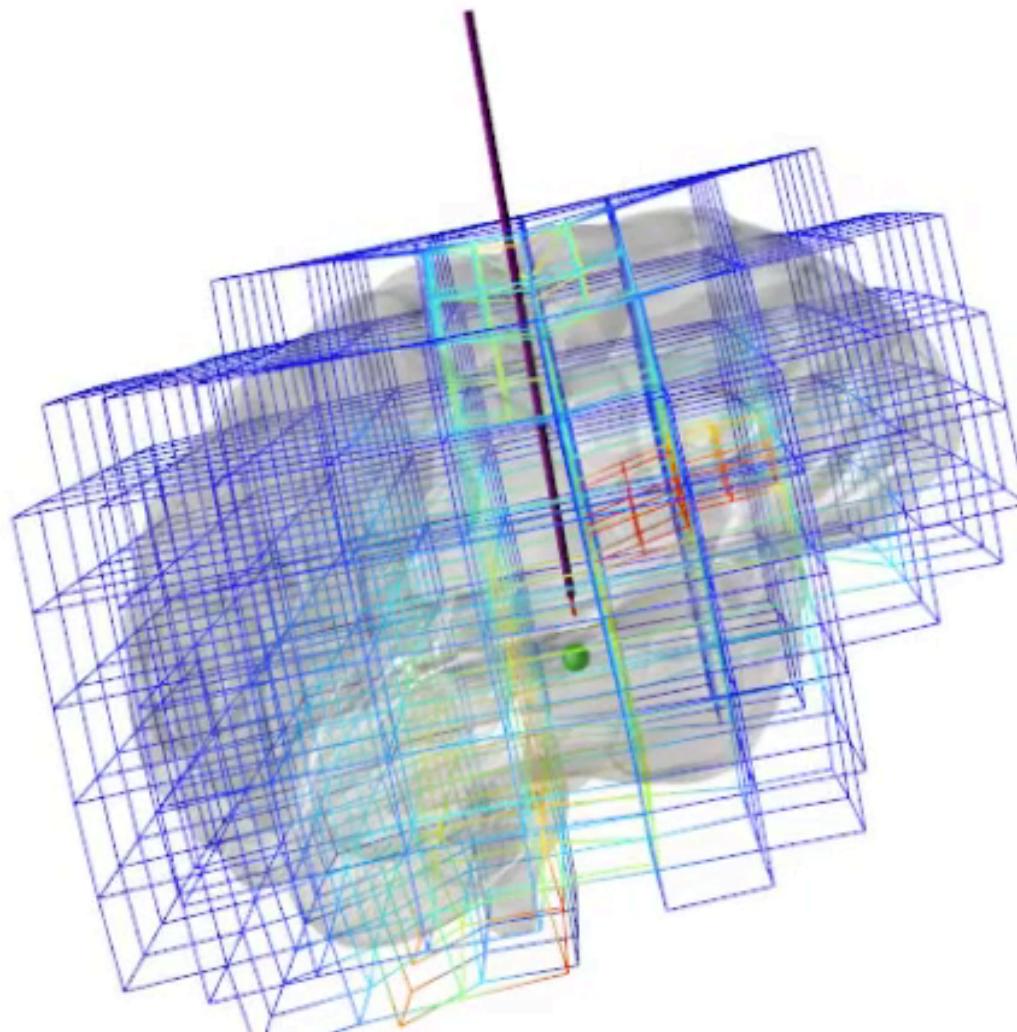
Engineering

Personalised medicine



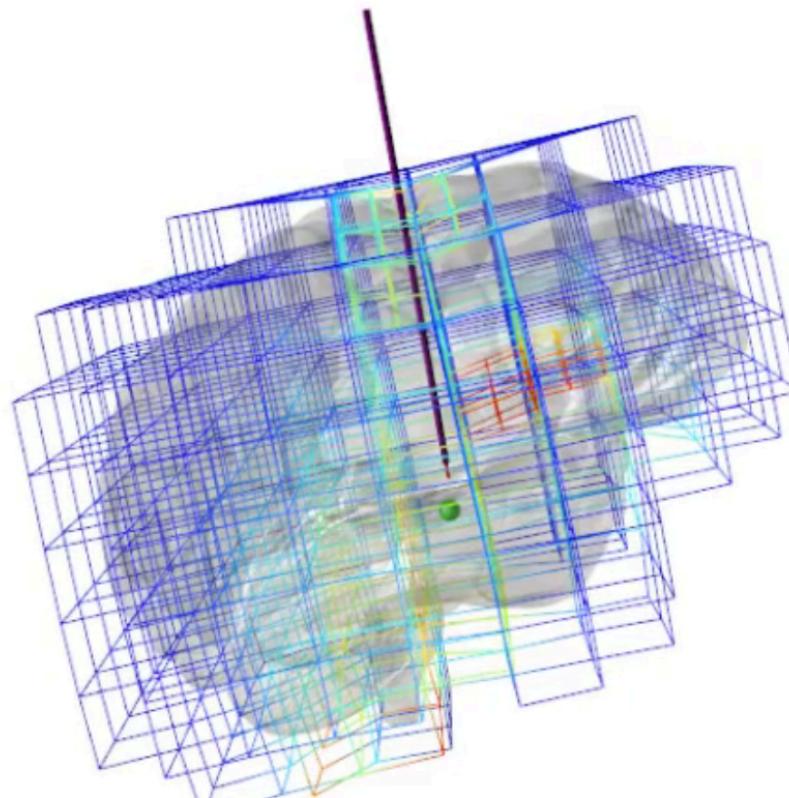
erc

Cannula insertion

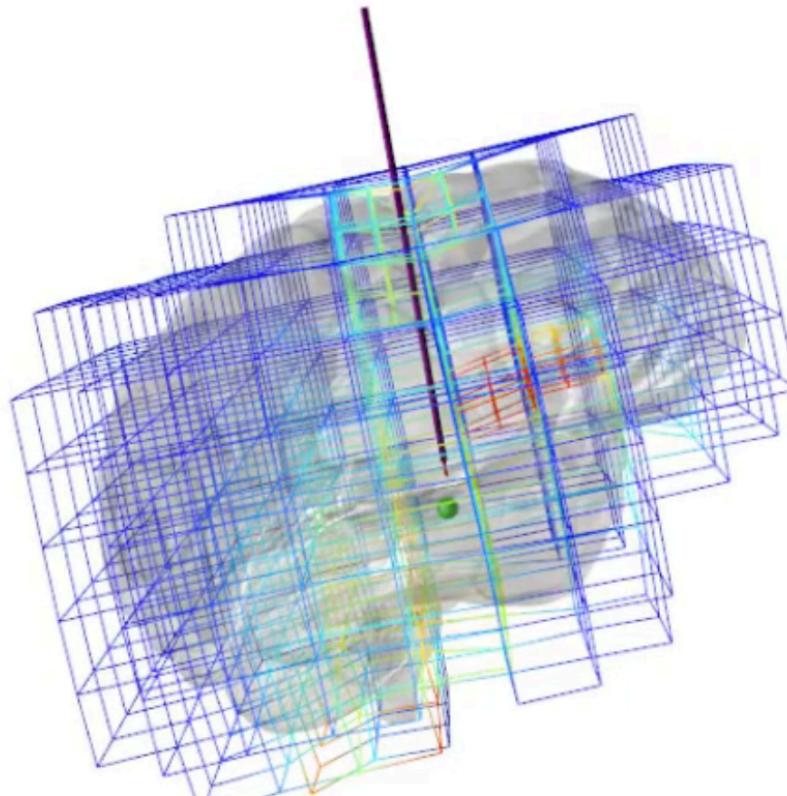


RealTCut

**CHALLENGE: everything happens
close to the needle... focus the
computational expense**



CHALLENGE: everything happens
close to the needle... focus the
computational expense



**But HOW to decide where and
what the element size should be?**

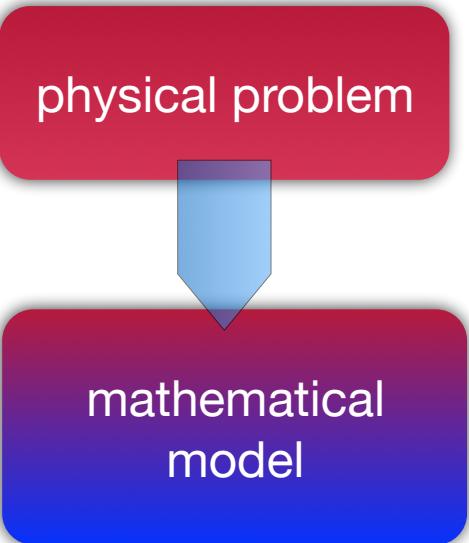


Quantify the quality of the simulation

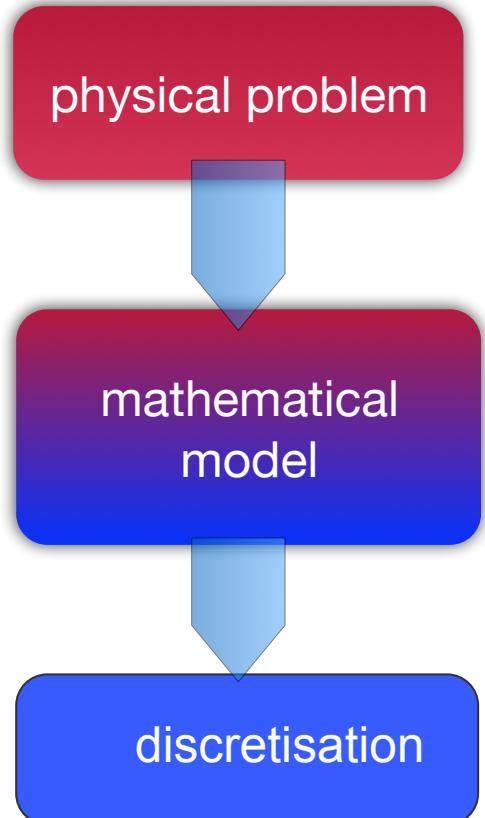
physical problem



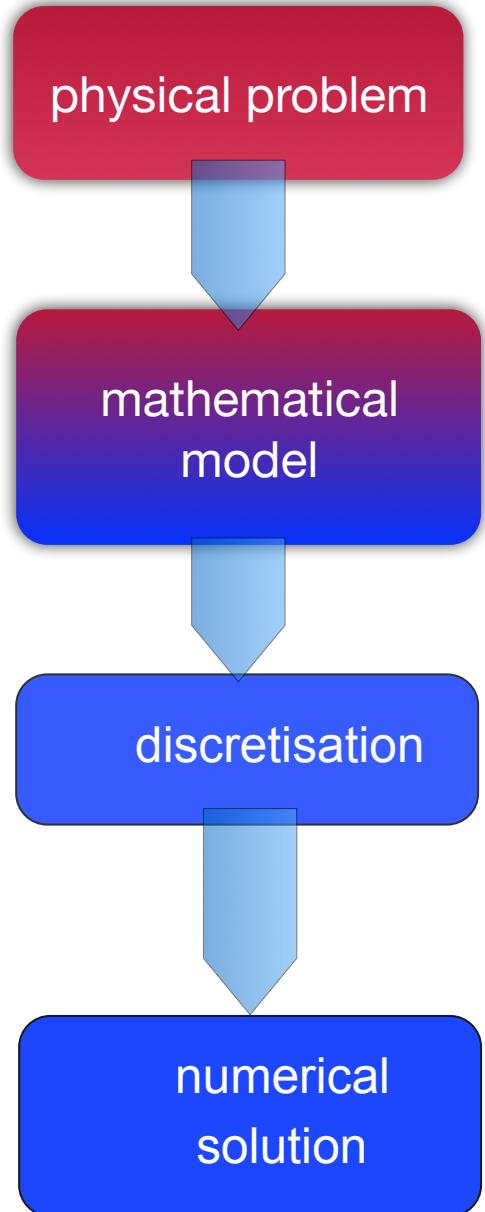
Quantify the quality of the simulation



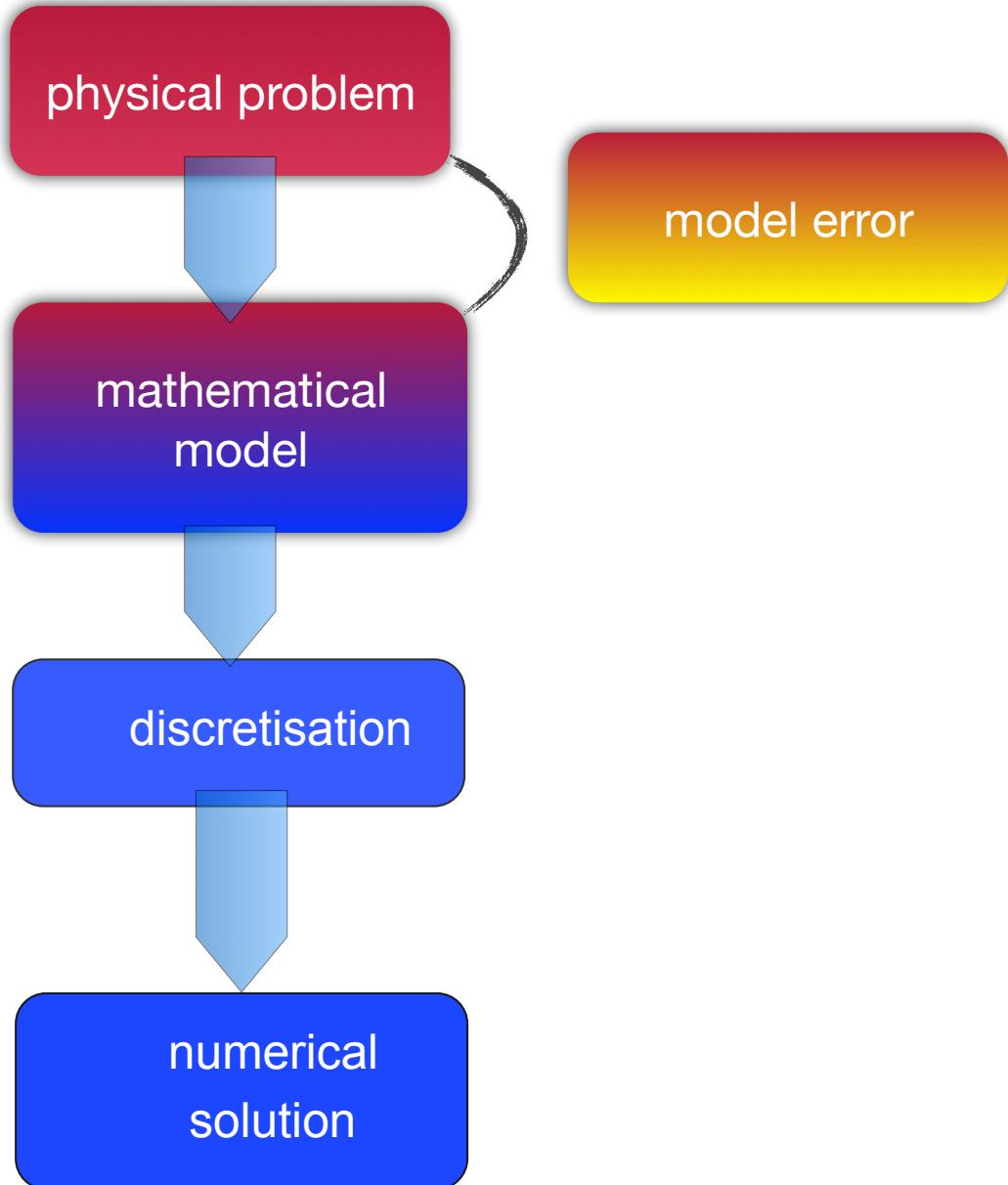
Quantify the quality of the simulation



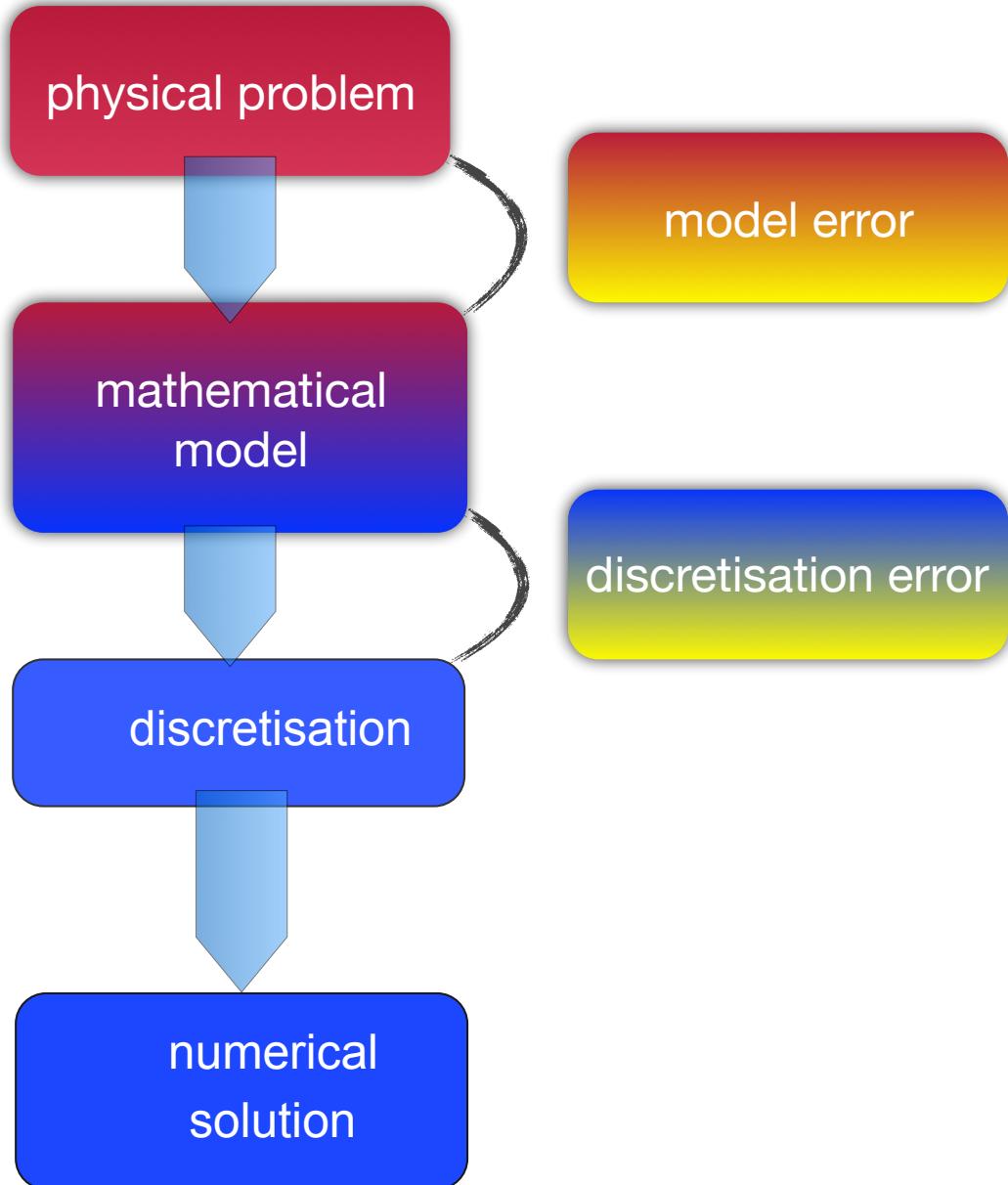
Quantify the quality of the simulation



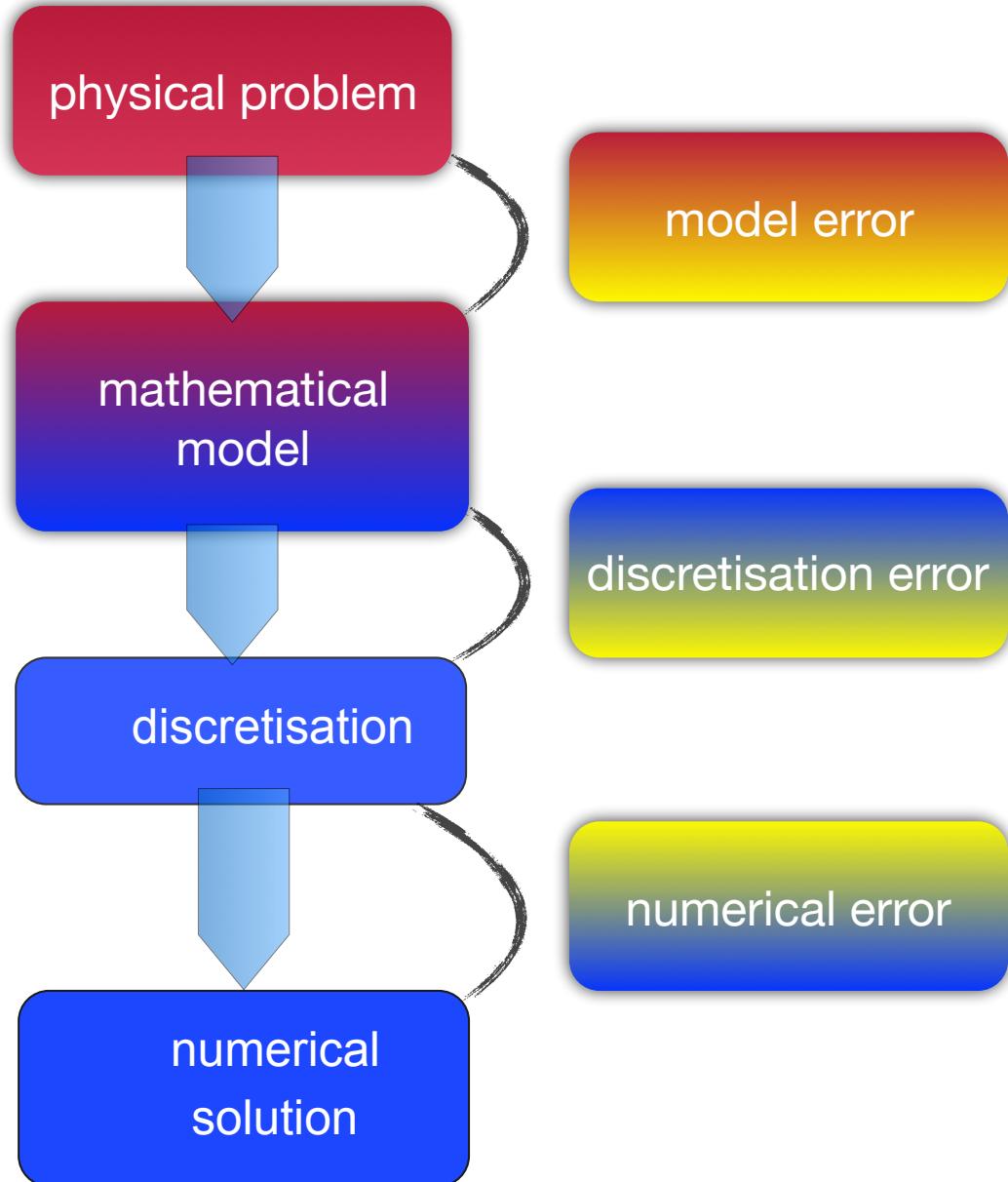
Quantify the quality of the simulation



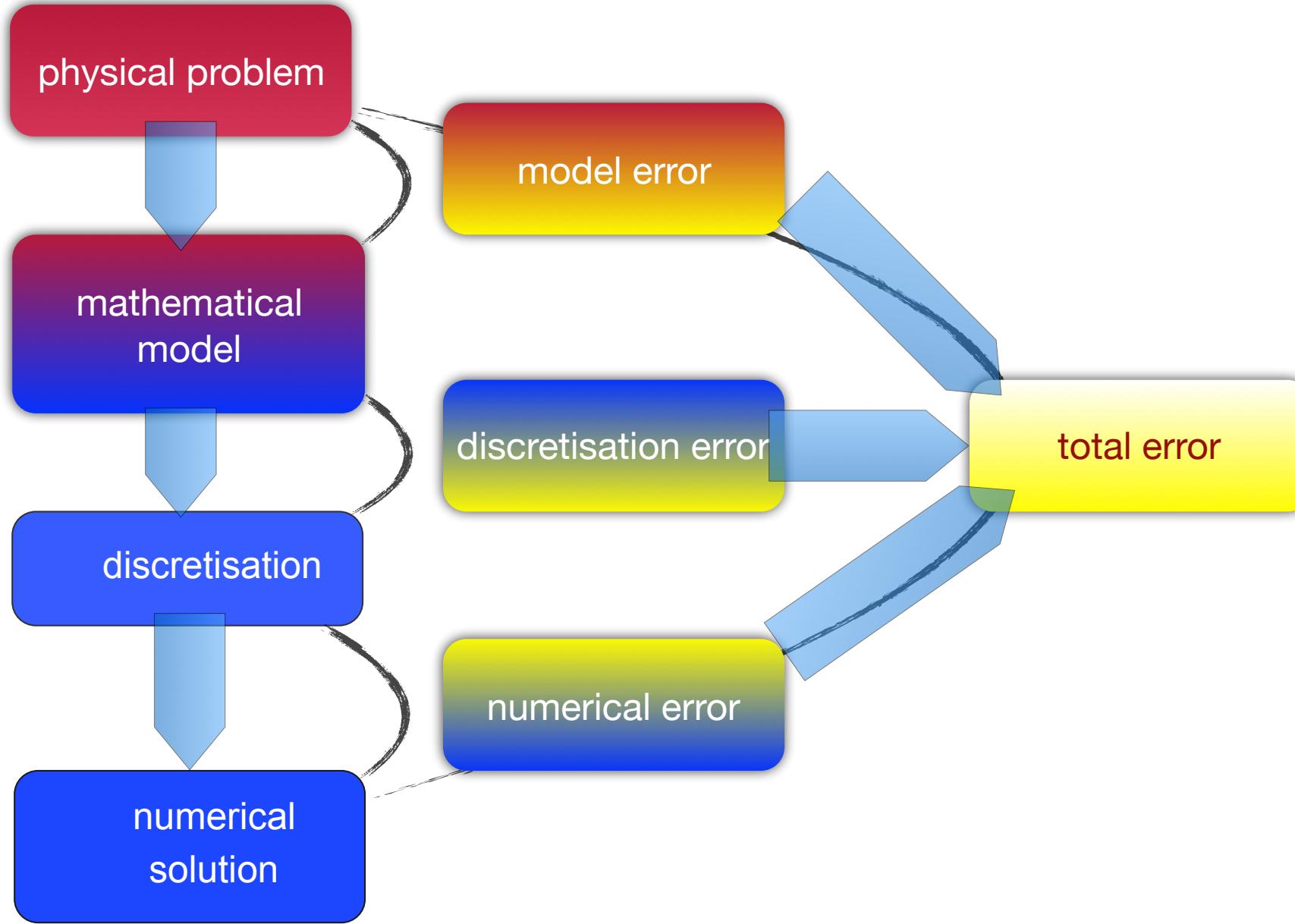
Quantify the quality of the simulation



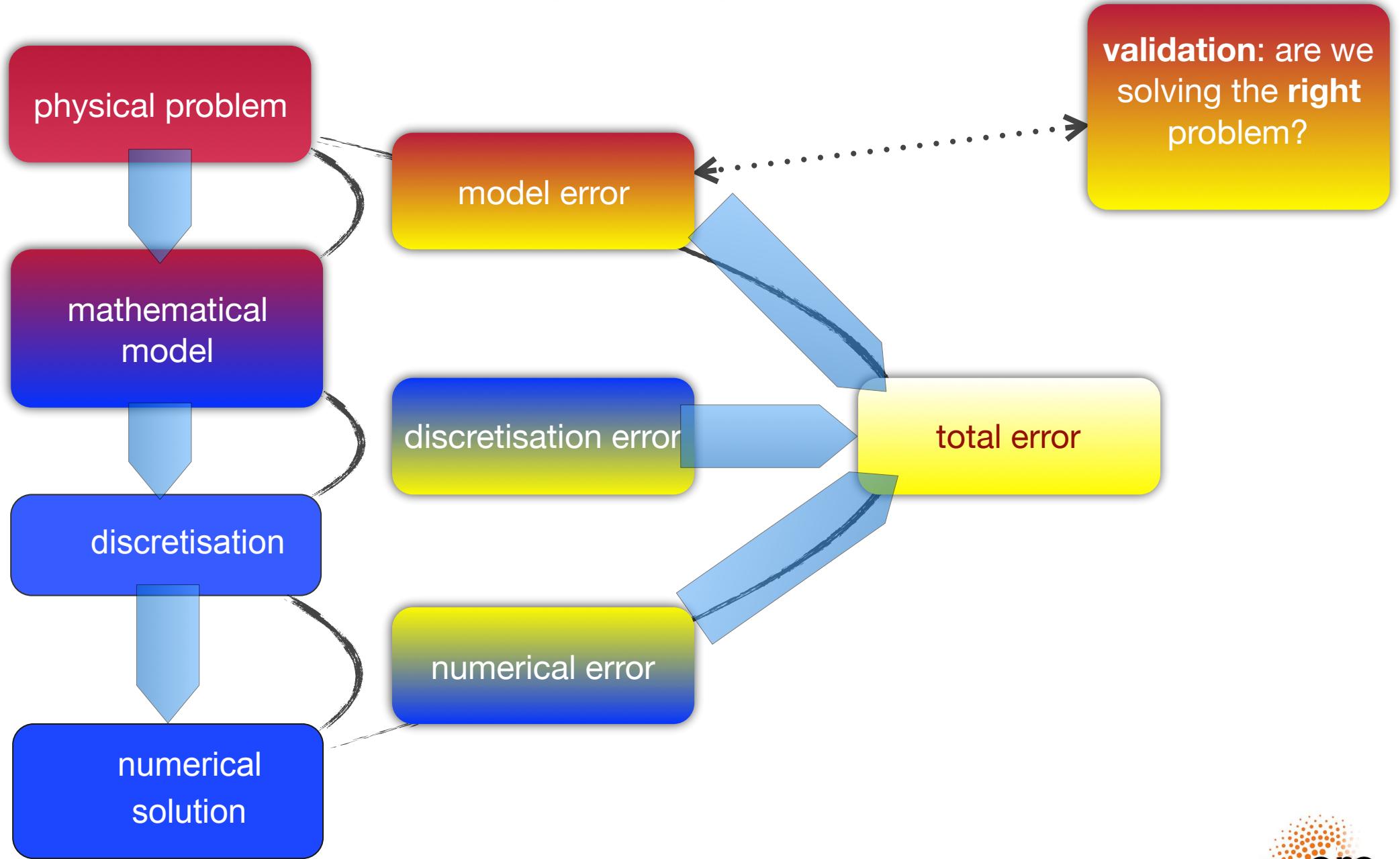
Quantify the quality of the simulation



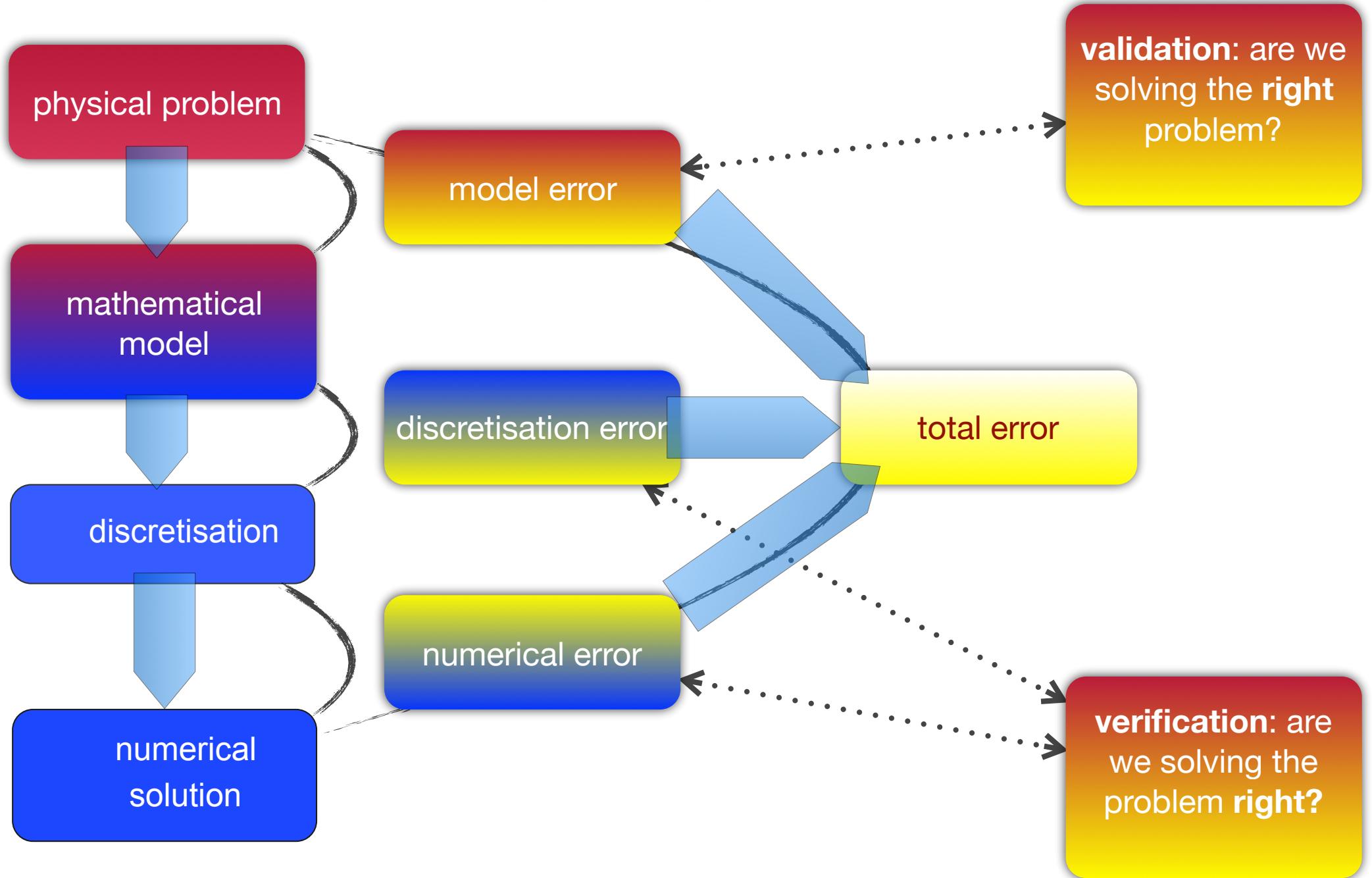
Quantify the quality of the simulation



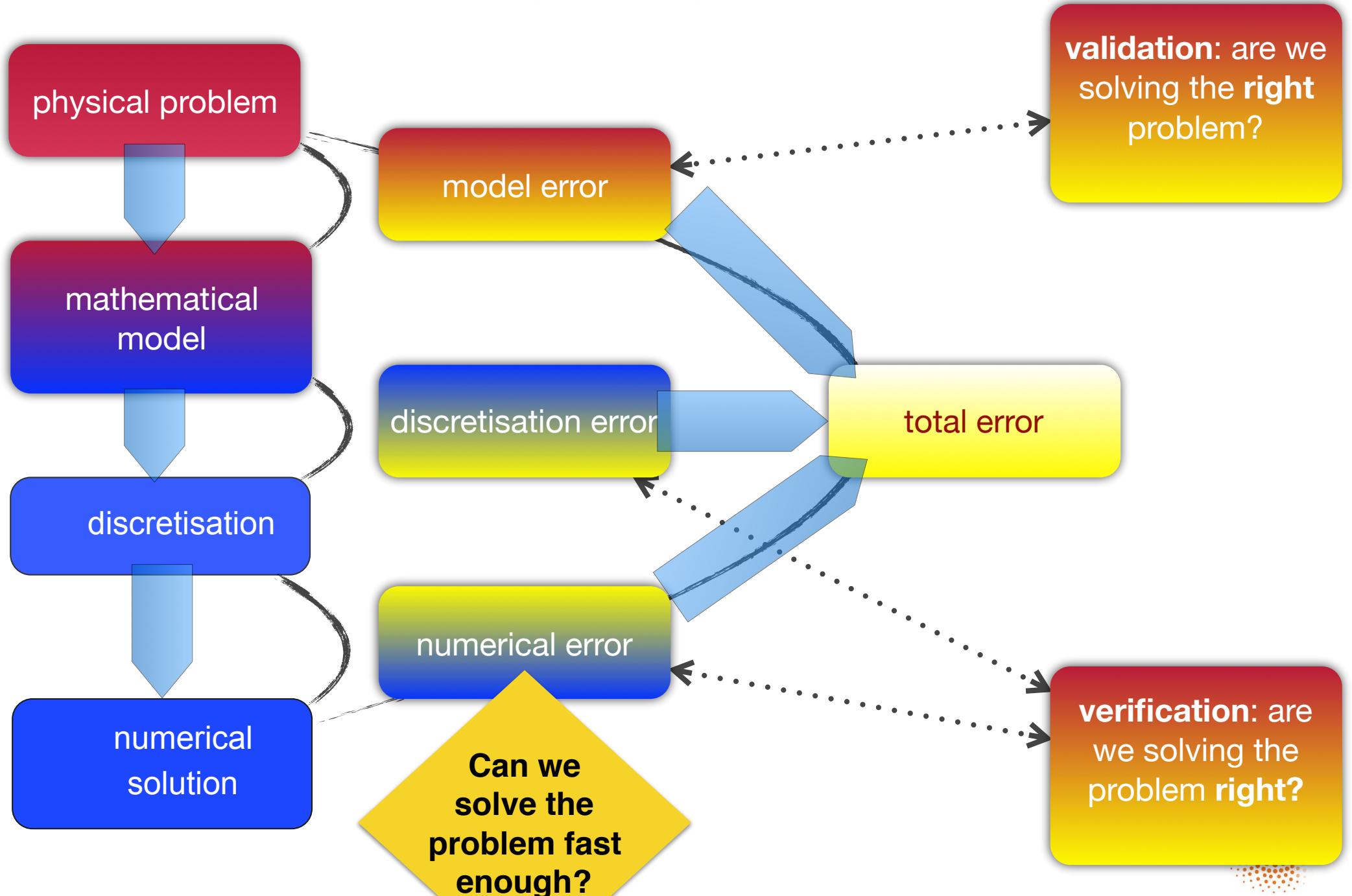
Quantify the quality of the simulation



Quantify the quality of the simulation



Quantify the quality of the simulation



ERC: first love



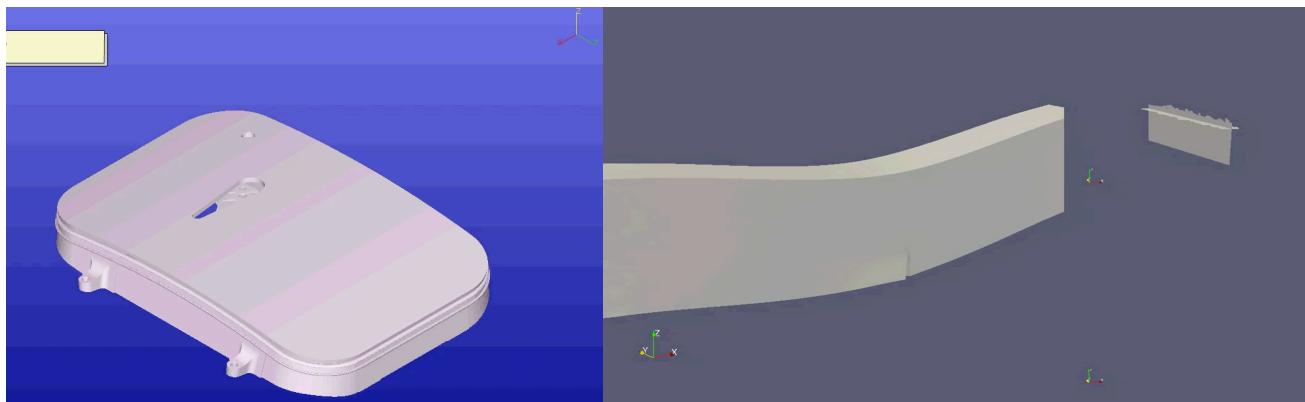
ERC: first love



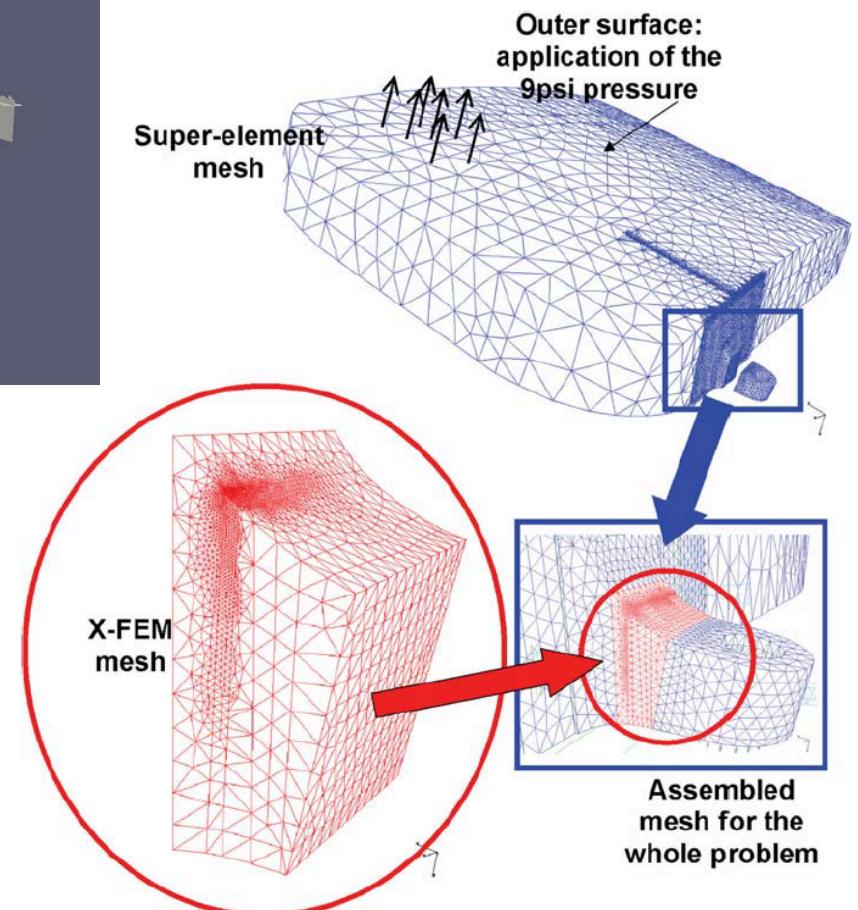
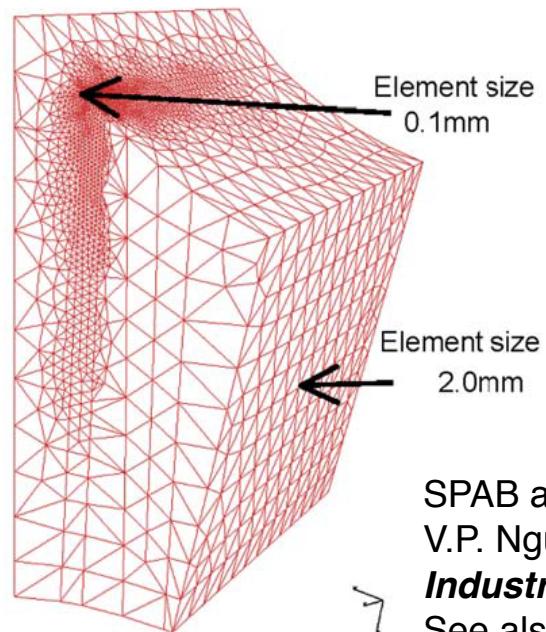
1999-2003 Damage Tolerance Assessment of Aerospace Structures PhD



How often should we inspect a structure for flaws?



ad hoc mesh refinement



SPAB and B. Moran, Engineering Fracture Mechanics, 2006

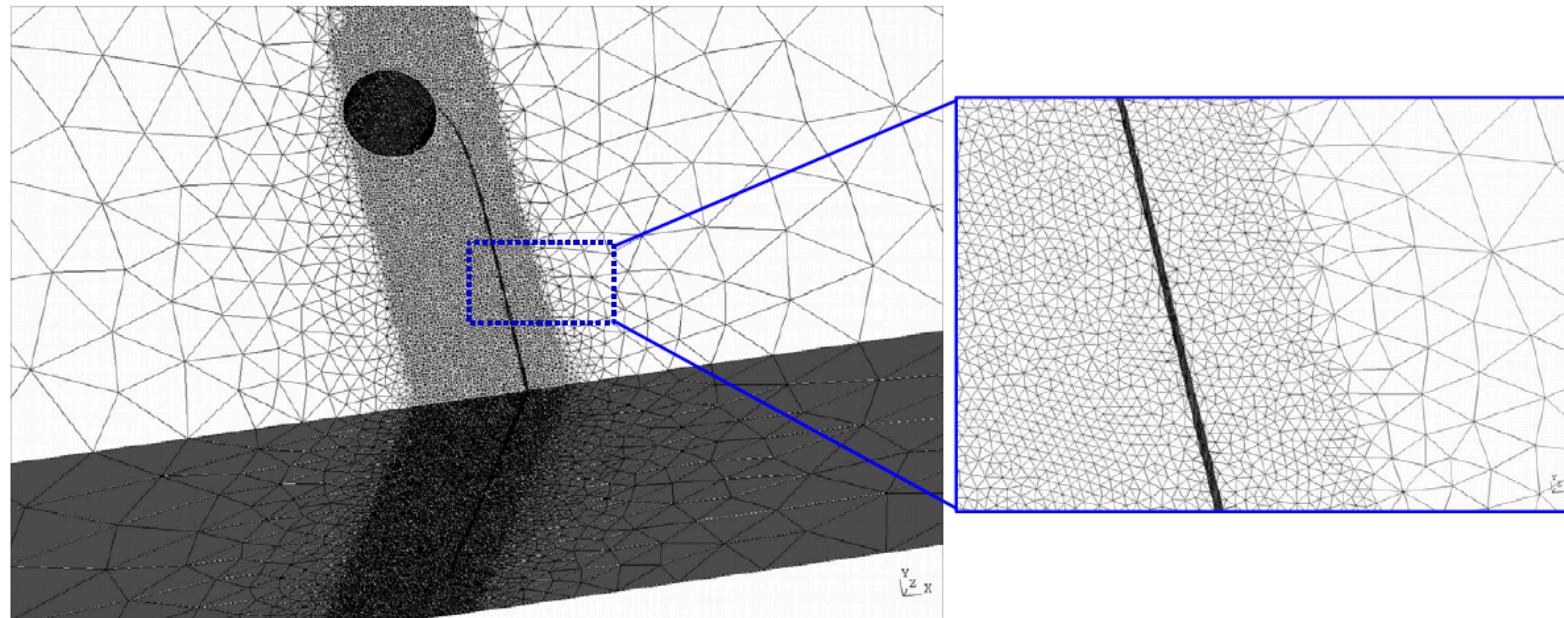
V.P. Nguyen et al. XFEM C++ Library IJNME, 2007

Industrial applications of extended finite element methods

See also E. Wyart et al, EFM, IJNME, 2008



Refine along the “expected” crack path...



Before: mesh “finely” in the region where the crack is “expected” to propagate

Y. Jin, O. Pierard, et al. Comput. Methods Appl. Mech. Engrg. 318 (2017) 319–348

O.A. González-Estrada et al. Computers and Structures 152 (2015) 1–10

O.A. González-Estrada et al. Comput Mech (2014) 53:957–976

C. Prange et al. IJNME 91.13 (2012): 1459–1474.

M. Duflot, SPAB, IJNME 2007, CNME 2007, IJNME 2008.

J-J. Ródenas Garcia, IJNME 2007

F.B. Barros, et al IJNME 60.14 (2004): 2373–2398.

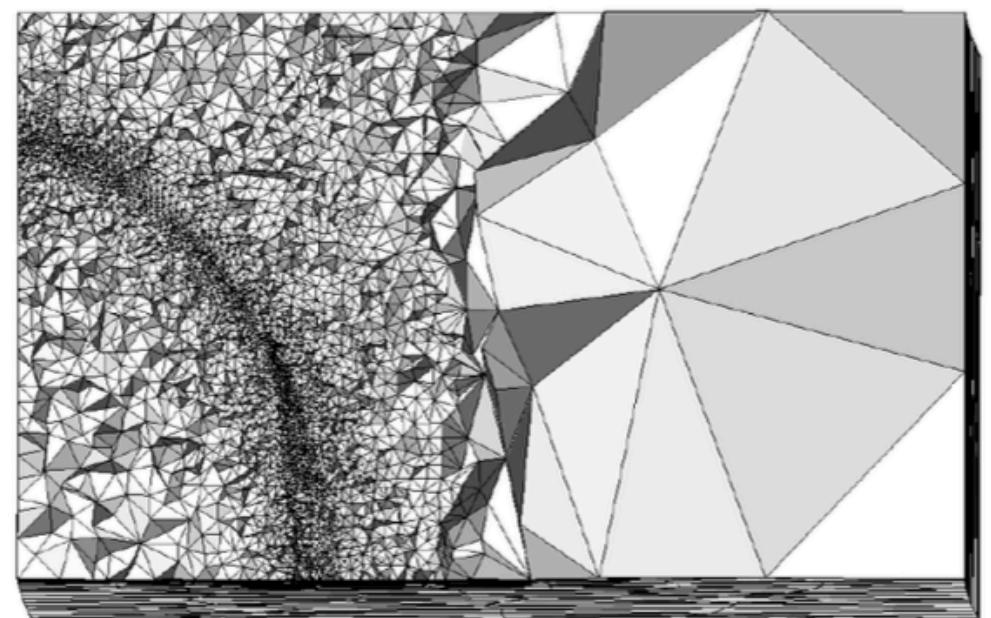
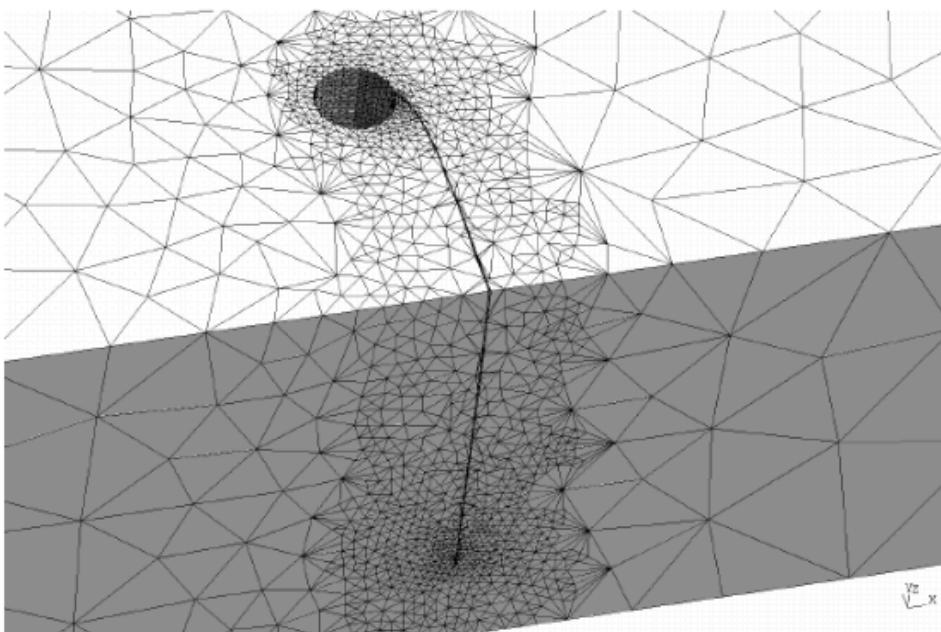
M. Rüter CMECH (2013) 1;52(2):361–76.

J. Panetier IJNME 81.6 (2010): 671–700.

P. Hild, CMECH (2010): 1–28.



Much better... adapt the discretisation locally

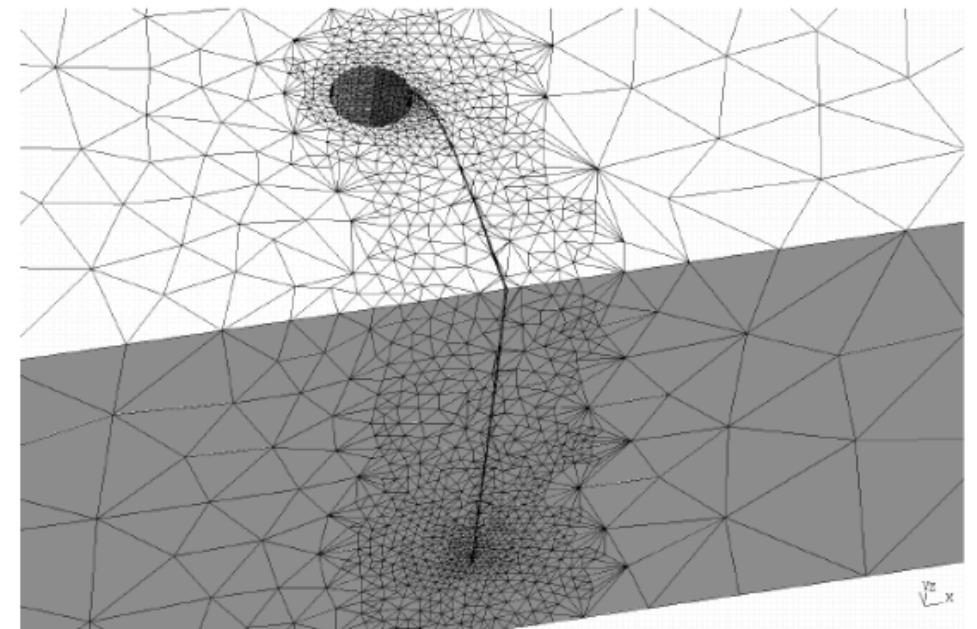
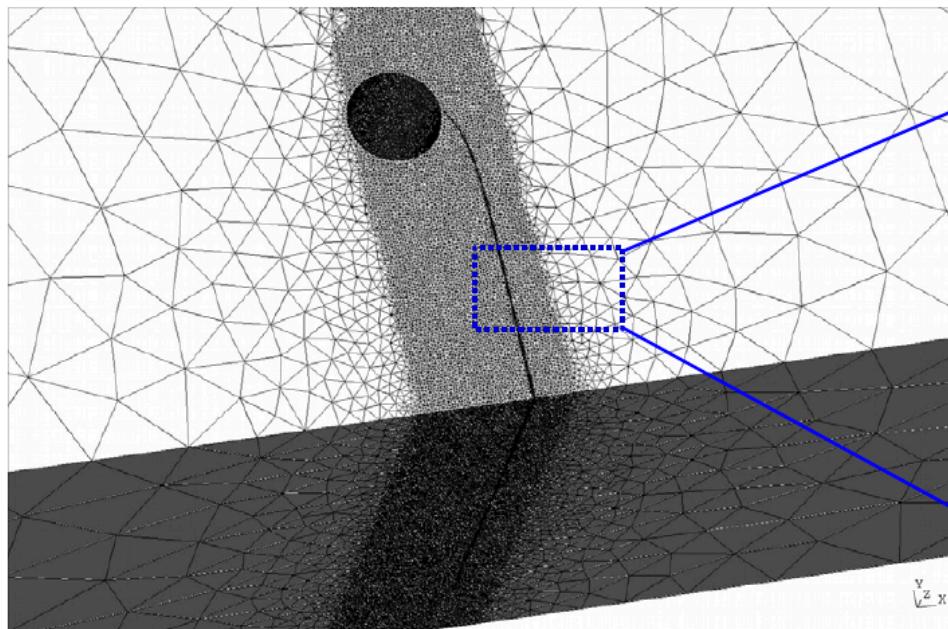


After: determine mesh refinement adaptively using a (goal-oriented) error estimate

Y. Jin, O. Pierard, et al. Error-controlled adaptive extended finite element method for 3D linear elastic crack propagation Comput. Methods Appl. Mech. Engrg. 318 (2017) 319–348
M. Duflot, SPAB, IJNME 2007, CNME 2007, IJNME 2008.



Much better... adapt the discretisation locally



Orders of magnitude fewer elements

Y. Jin, O. Pierard, et al. Error-controlled adaptive extended finite element method for 3D linear elastic crack propagation Comput. Methods Appl. Mech. Engrg. 318 (2017) 319–348
M. Duflot, SPAB, IJNME 2007, CNME 2007, IJNME 2008.



From your first love to the ERC



hiking - 20km D+500m



ultra-marathon 52km D+2500m



aerospace

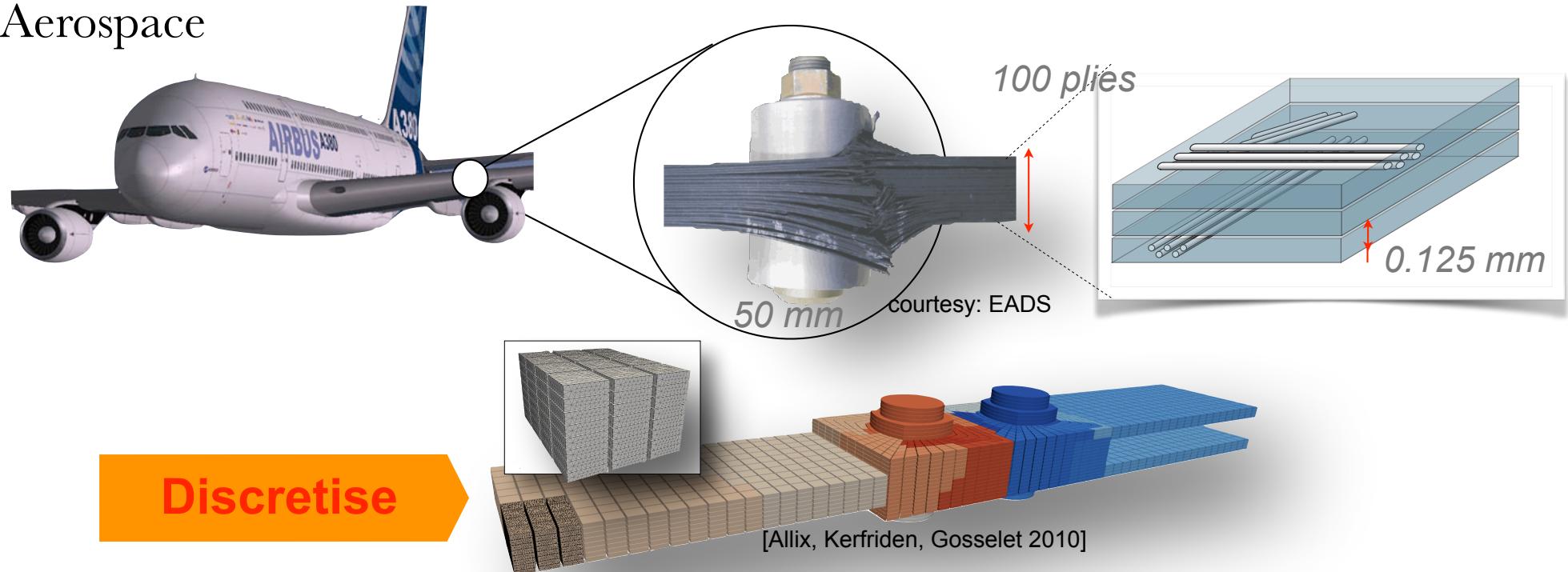


biomechanics

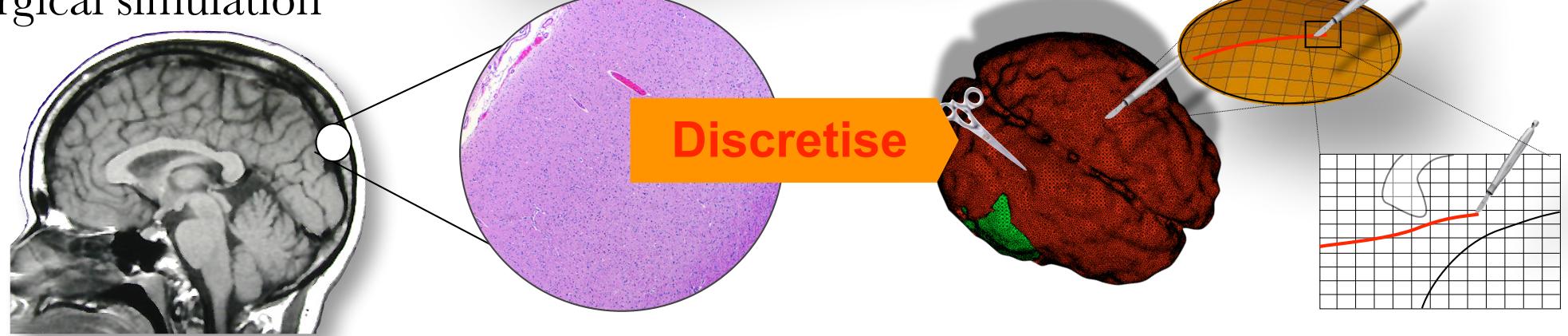


Motivation: multiscale fracture of engineering structures and materials

Aerospace

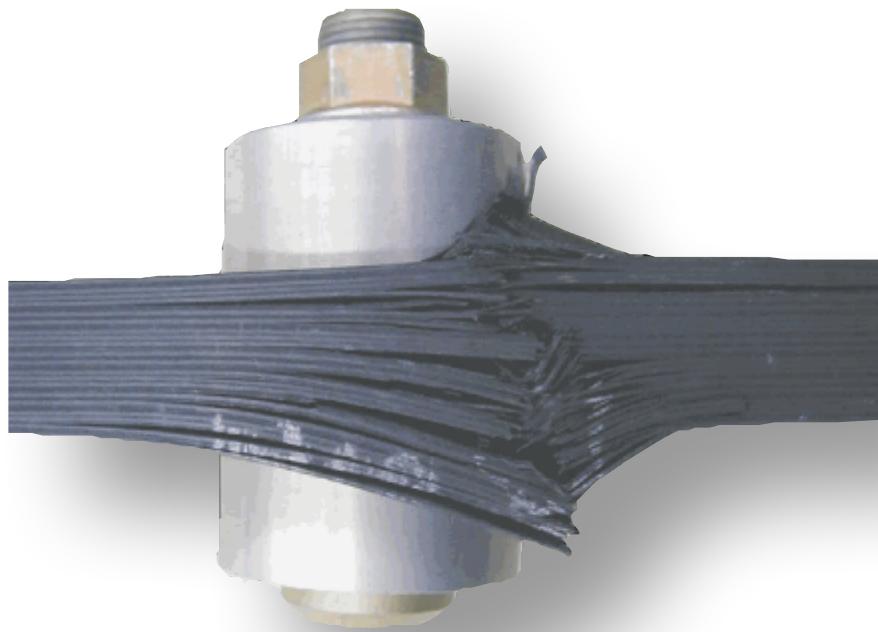


Surgical simulation

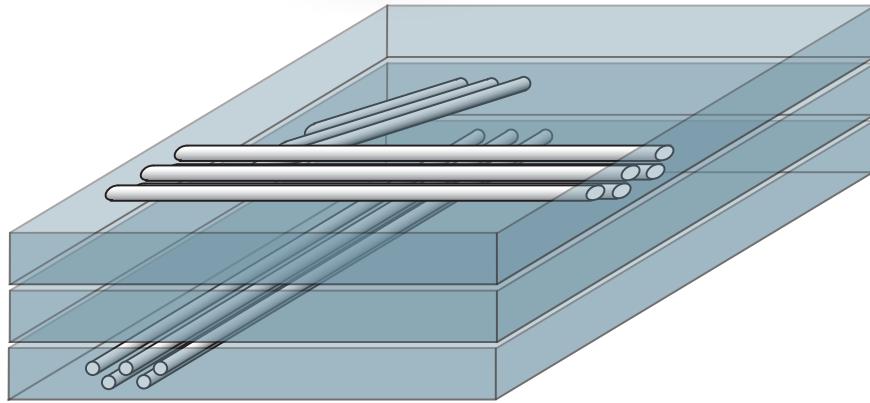


- Reduce the problem size while controlling the quality for problems involving (free) interfaces

Aero

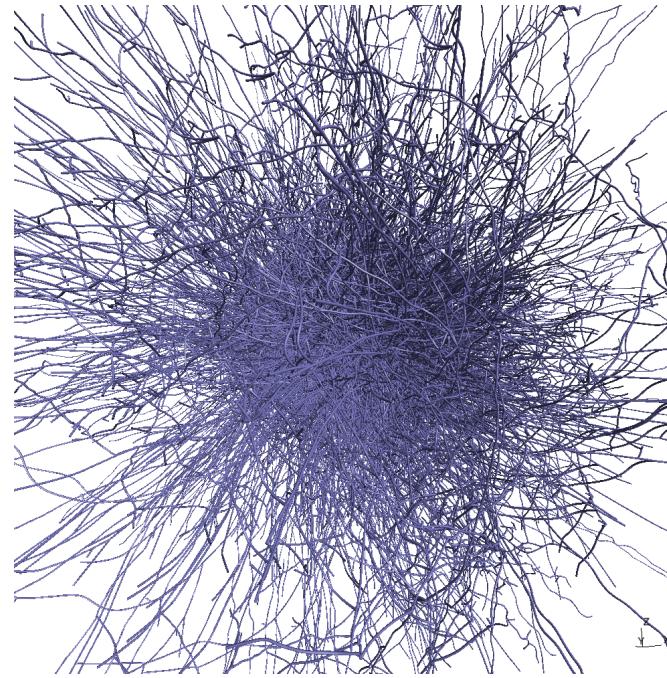


Bolted joint Courtesy EADS

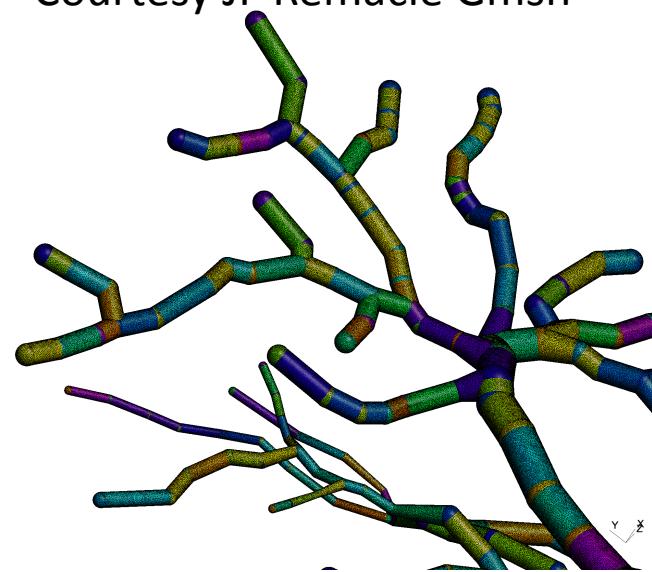


Multi-scale fibre lay-up Courtesy EADS

Bio



Courtesy JF Remacle Gmsh

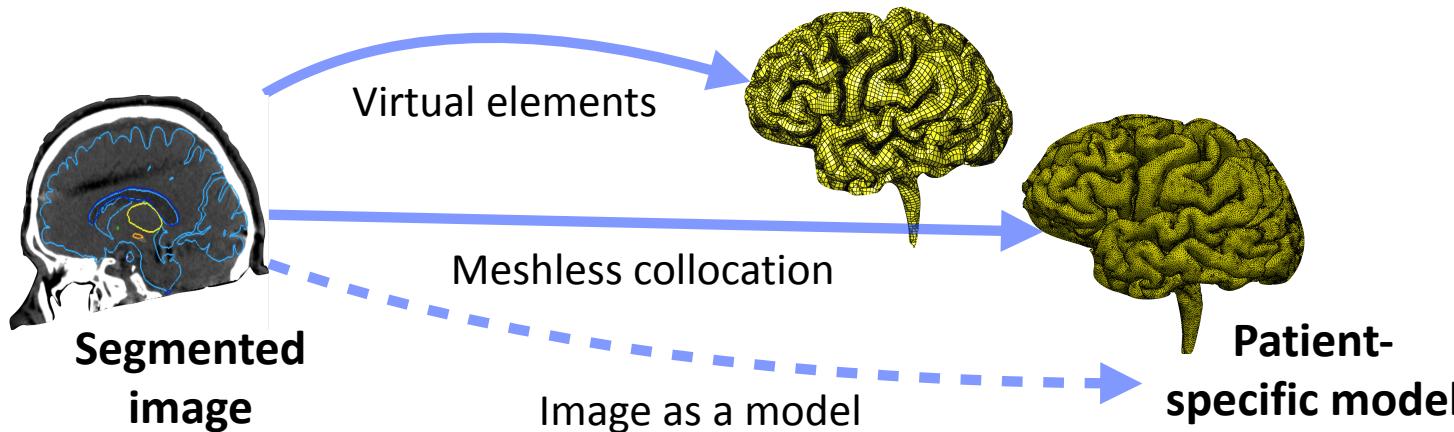


Courtesy JF Remacle Gmsh



MAIN RESULT: QUALITY-CONTROLLED REAL-TIME SIMULATION

Represent numerically the geometry of a given patient

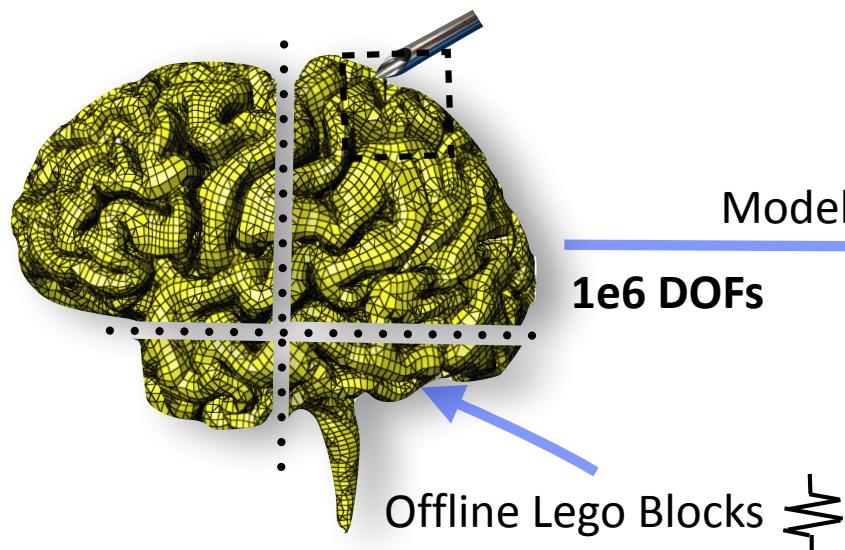


Research questions

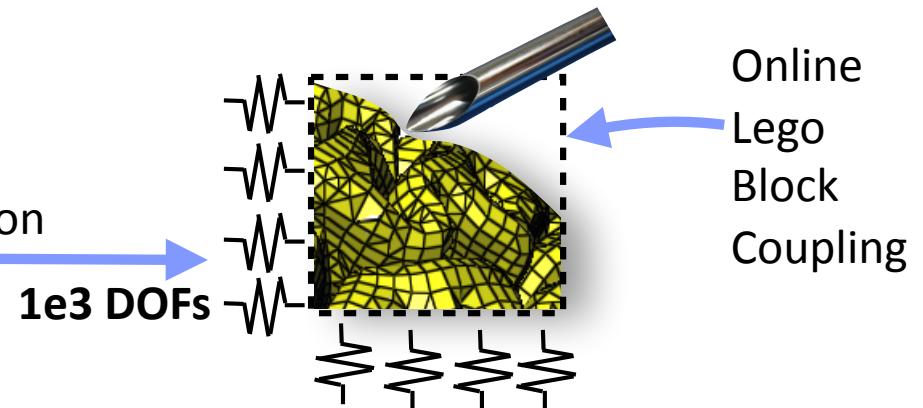
- ▶ Generation speed?
- ▶ Easy adaptivity?
- ▶ Incompressibility?
- ▶ Mesh distortion?

Solve the problem fast enough and with quality control

Precompute OFFLINE



Real-time ONLINE

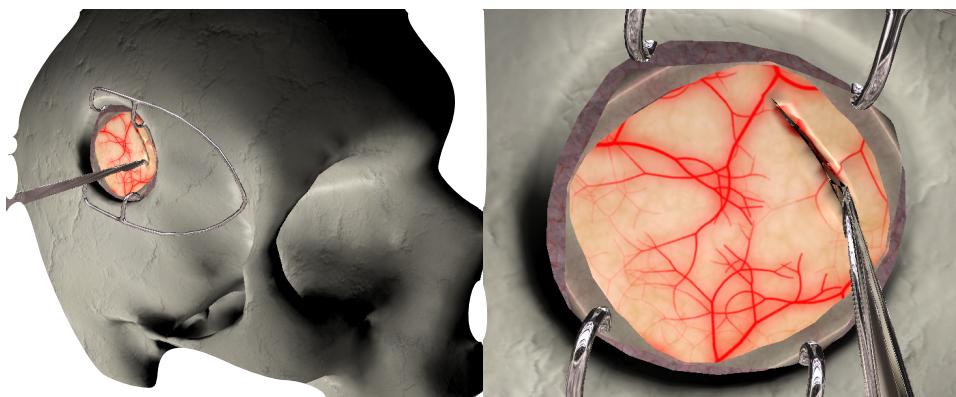


NEXT CHALLENGES

ERC ReaTCut

Train surgeons safely on simulators

- ▶ Generic material models: *a priori*.
- ▶ Errors in quantities of interest for cuts in linear materials.
- ▶ Interactive simulations (solution in ms).



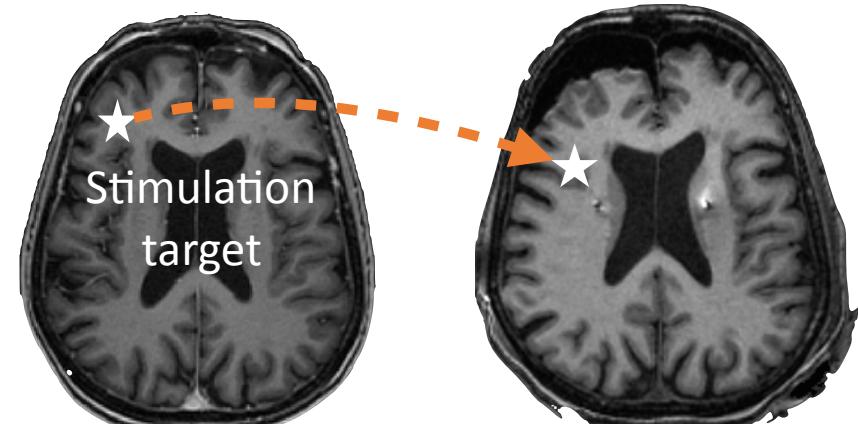
Courtecuisse, 2014, *Implicit method for cutting in real-time*. MEDIA

A generic organ is sufficient.

Future

Surgical assistance and planning

- ▶ Data-driven material models (real-time).
- ▶ Error control in quantities of interest for strong non-linearities, multi-field...
- ▶ Clinical time scales (solution in minutes).

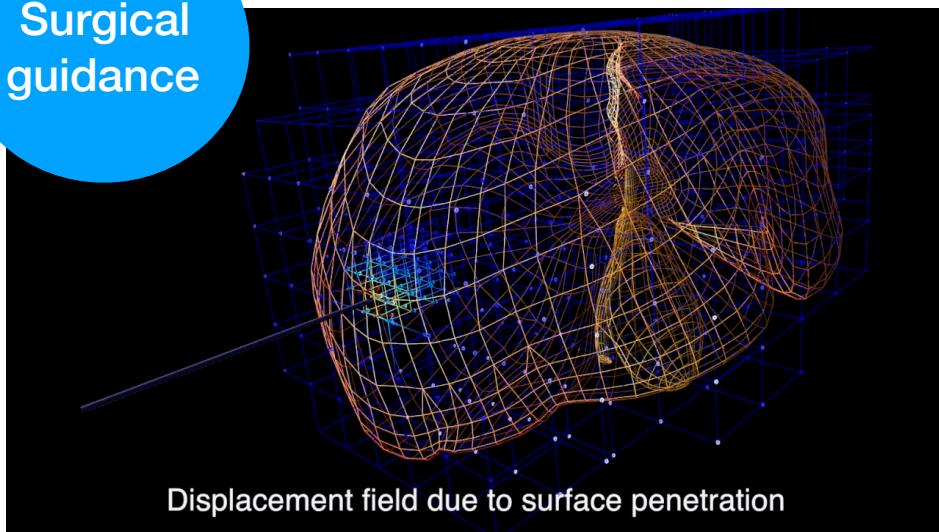


Predict shift of brain target.

Patient specificity is essential.

From surgical training to surgical planning and assistance

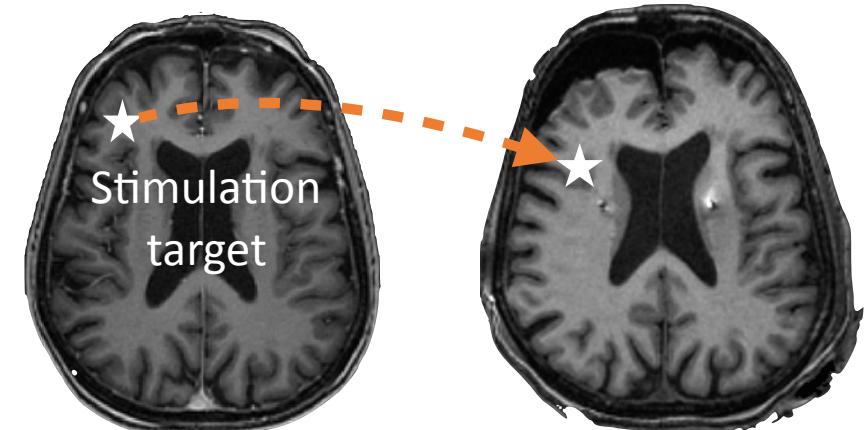
Surgical
guidance



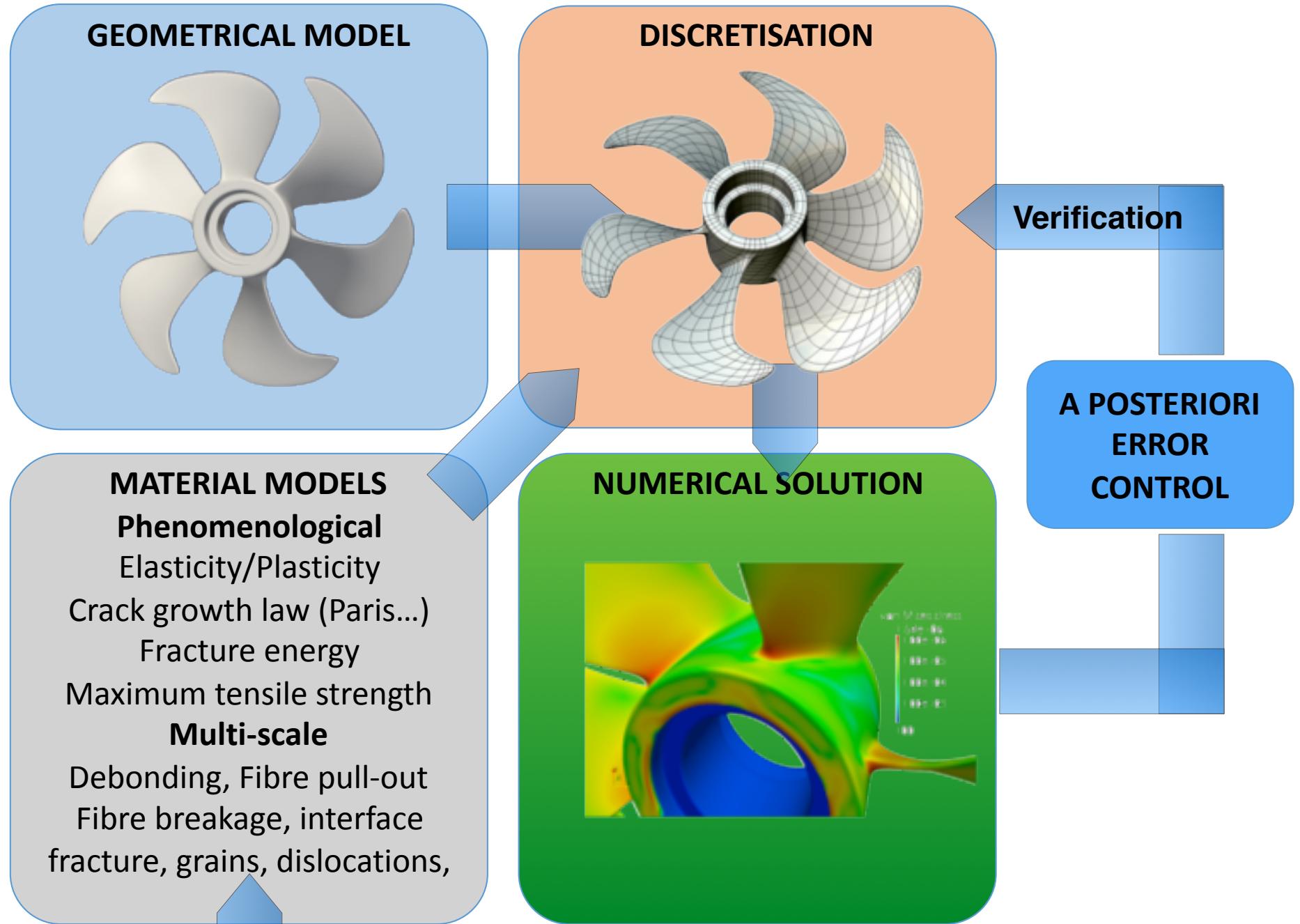
QUESTION: What (material)
model should be used for a given
patient?

Future Surgical assistance and planning

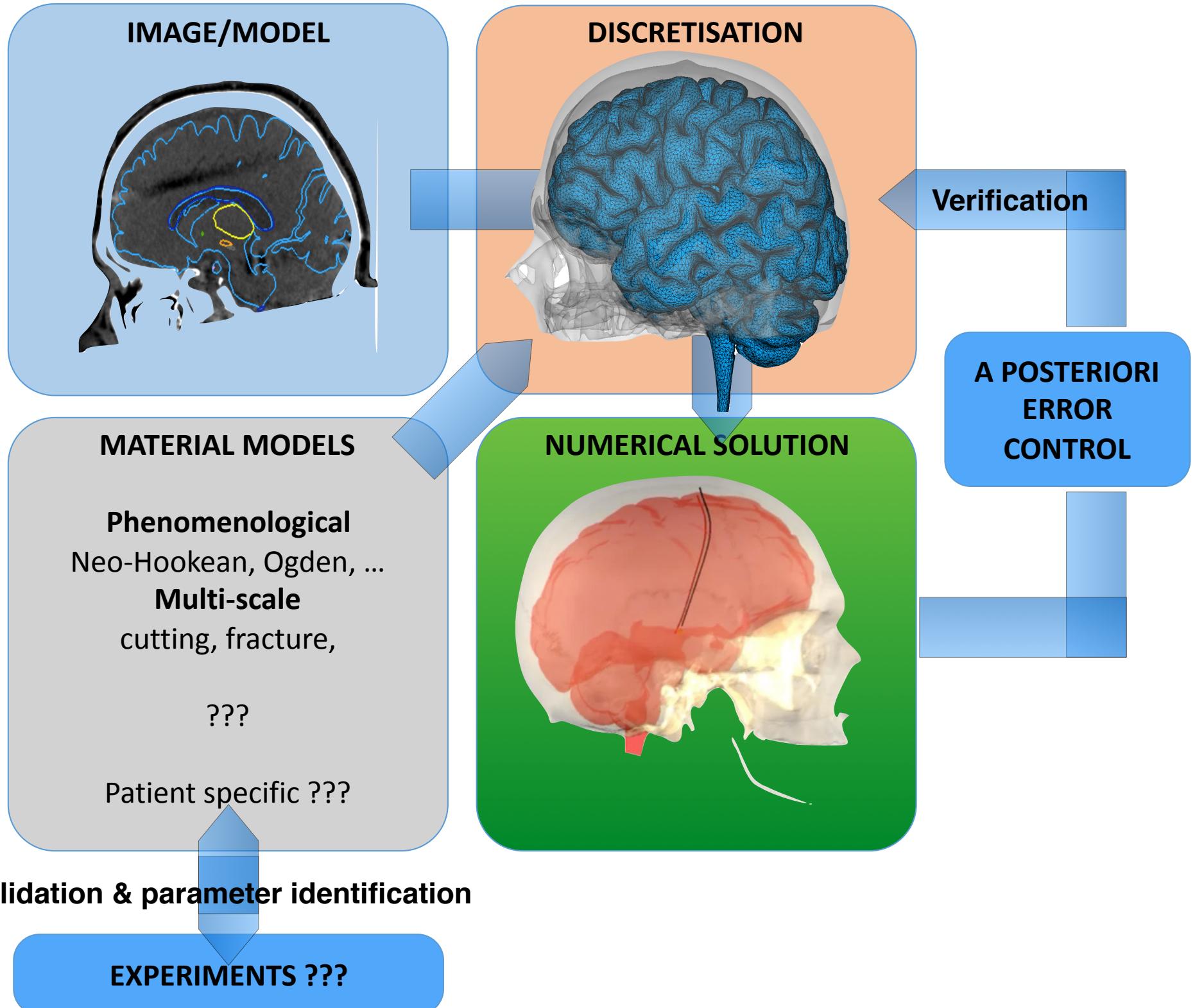
- ▶ Data-driven material models (real-time).
- ▶ Error control in quantities of interest for strong non-linearities, multi-field...
- ▶ Clinical time scales (solution in minutes).



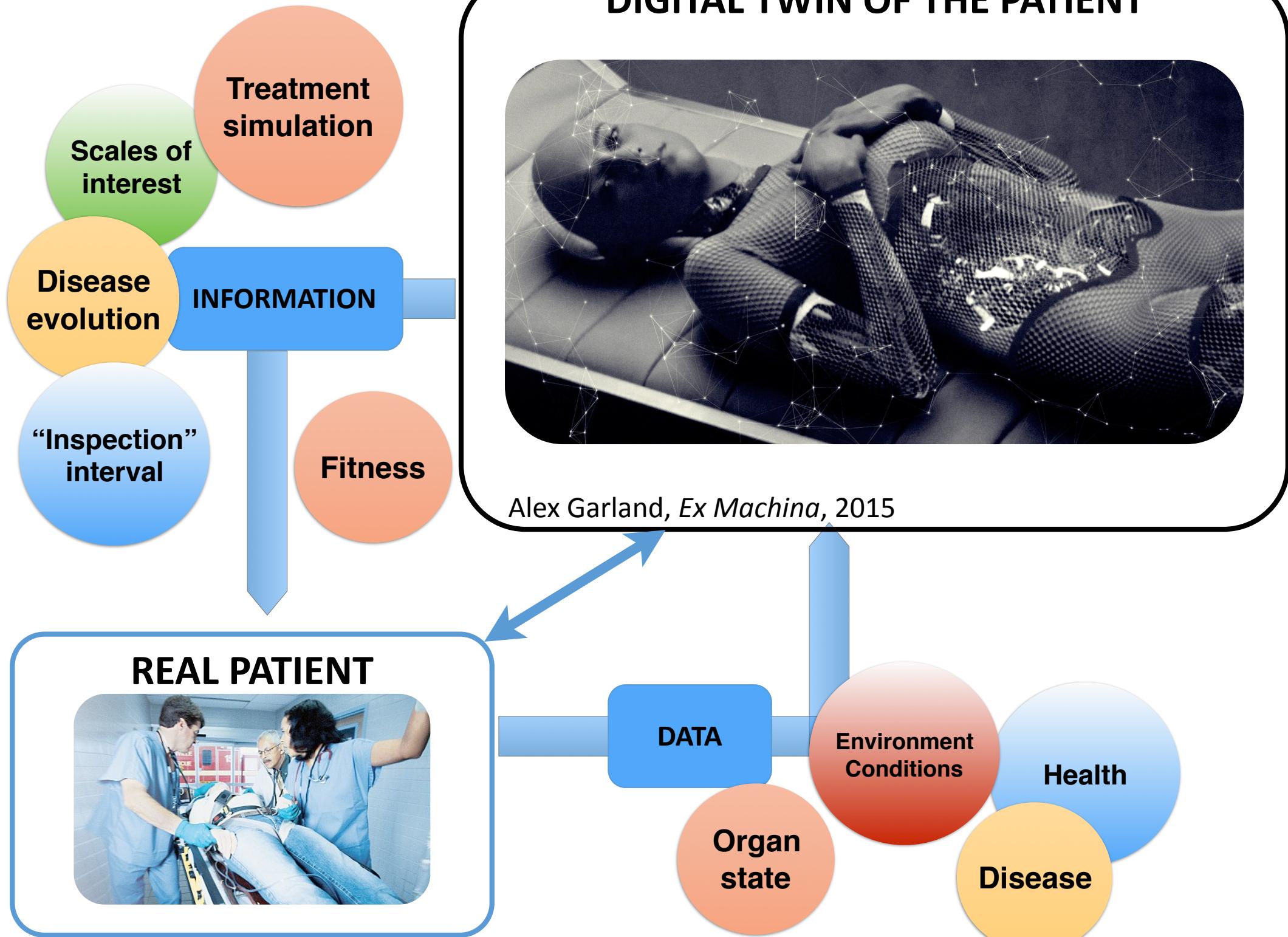
Patient specificity is essential.



CONVENTIONAL APPROACH



DIGITAL TWIN OF THE PATIENT

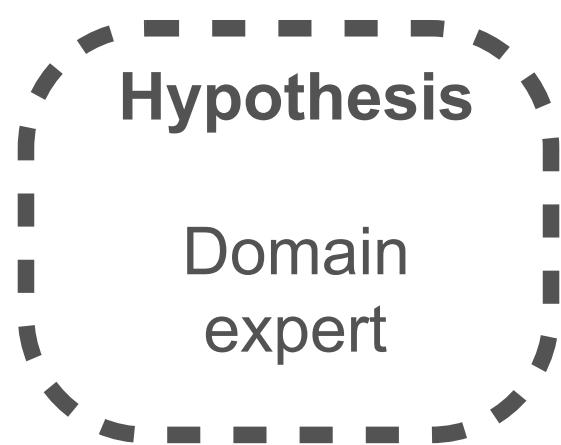




Prior Knowledge

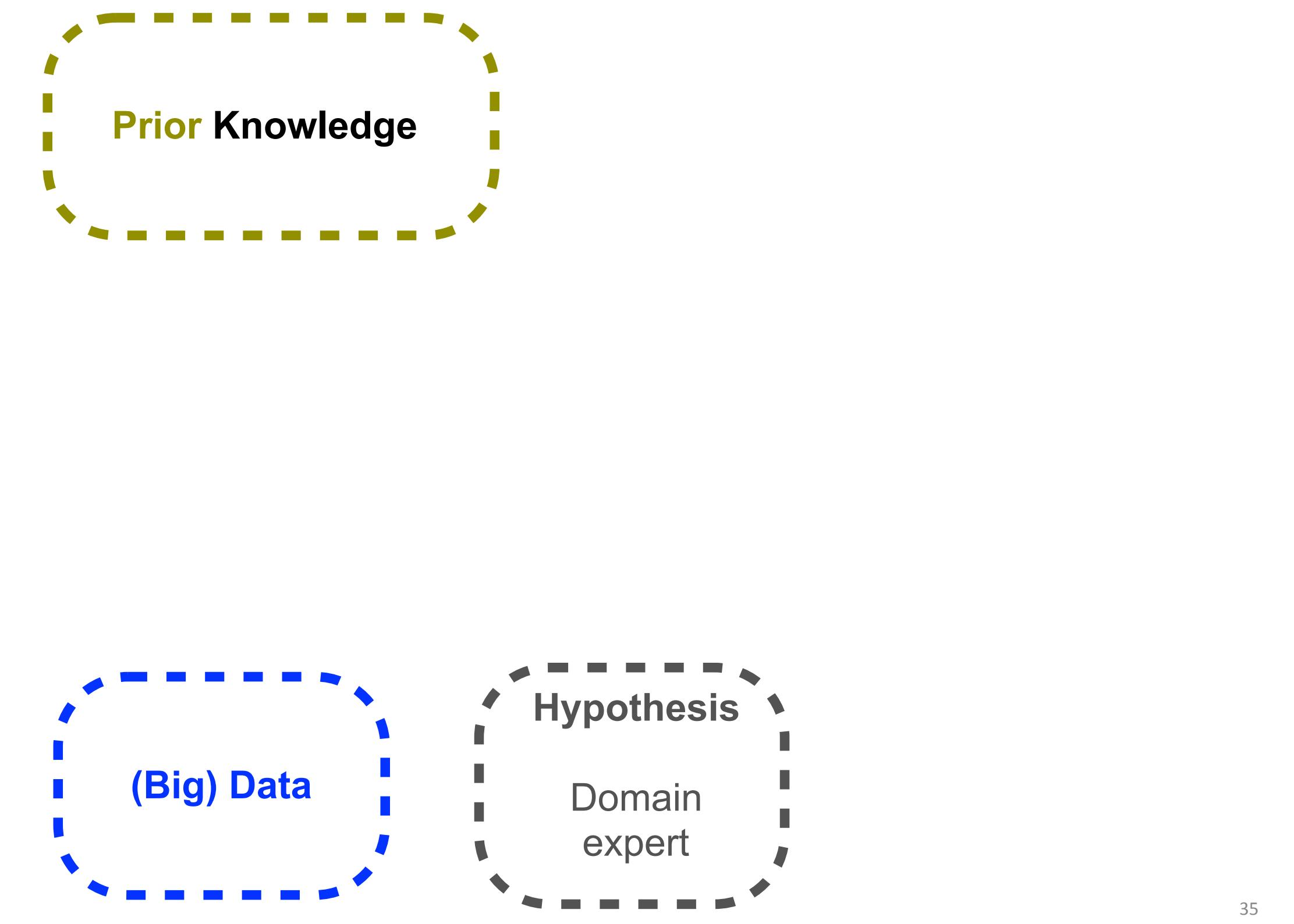


Prior Knowledge



Hypothesis

Domain
expert



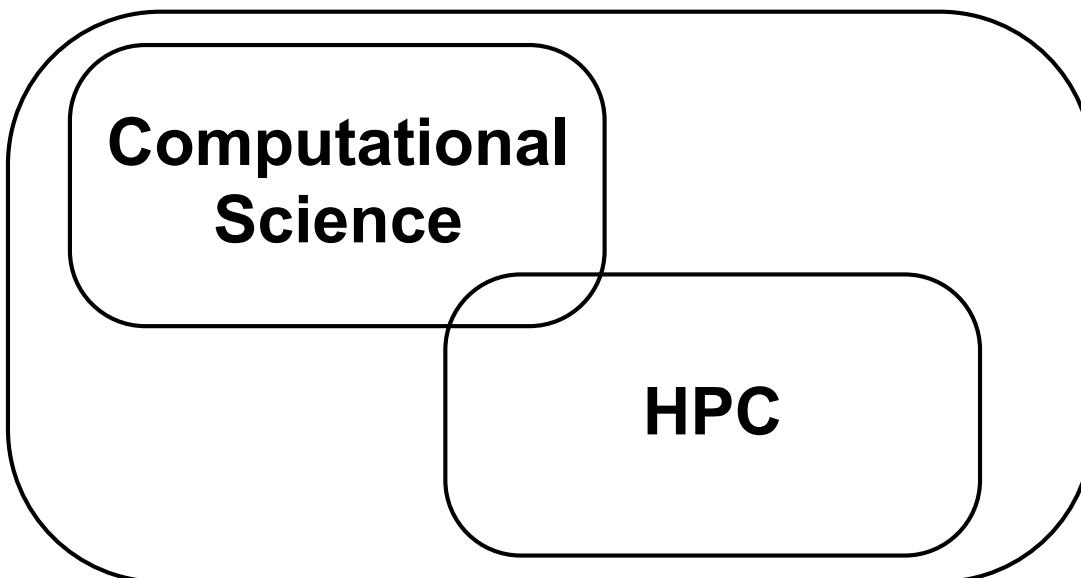
Prior Knowledge

(Big) Data

Hypothesis

Domain
expert

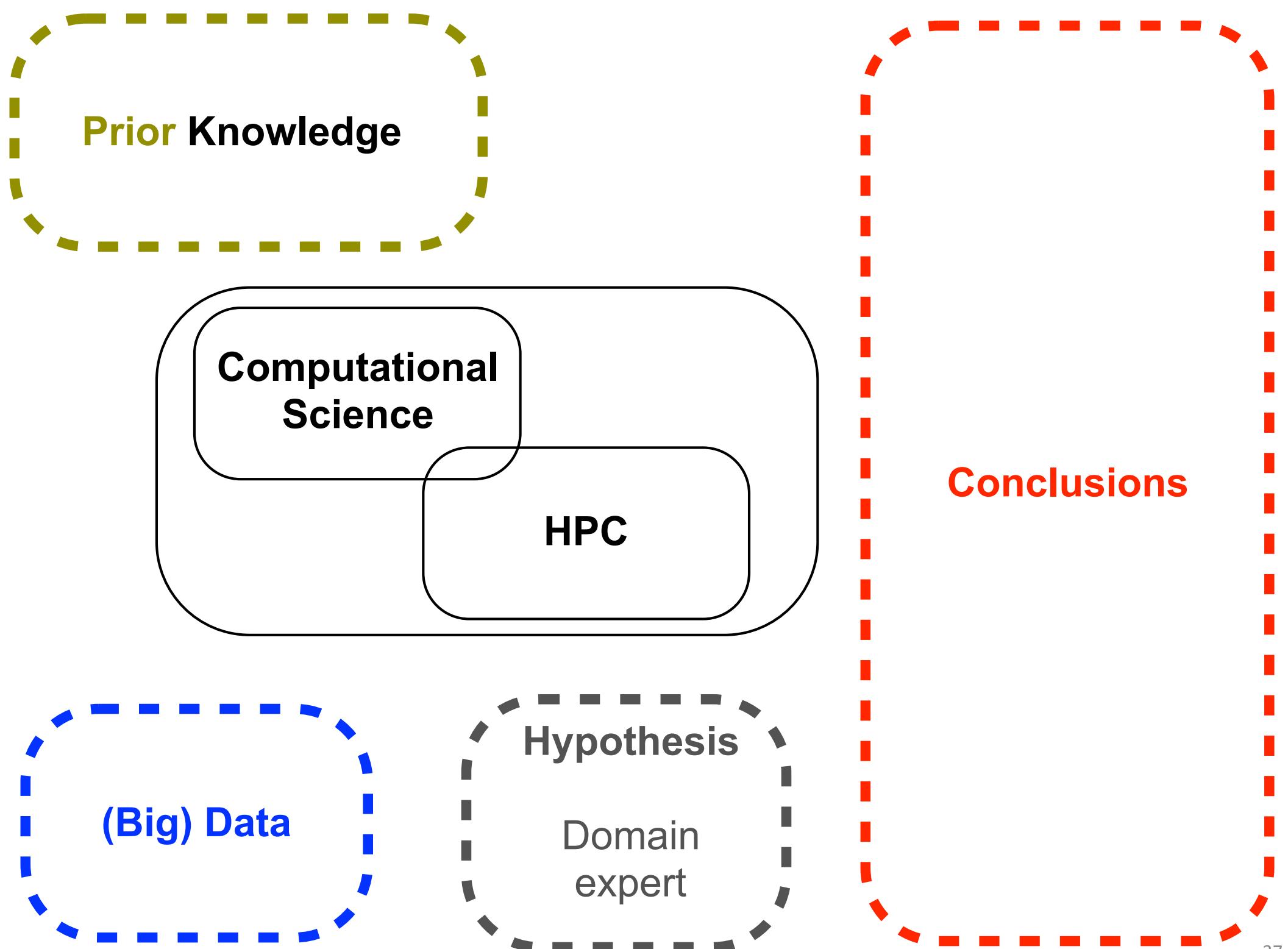
Prior Knowledge

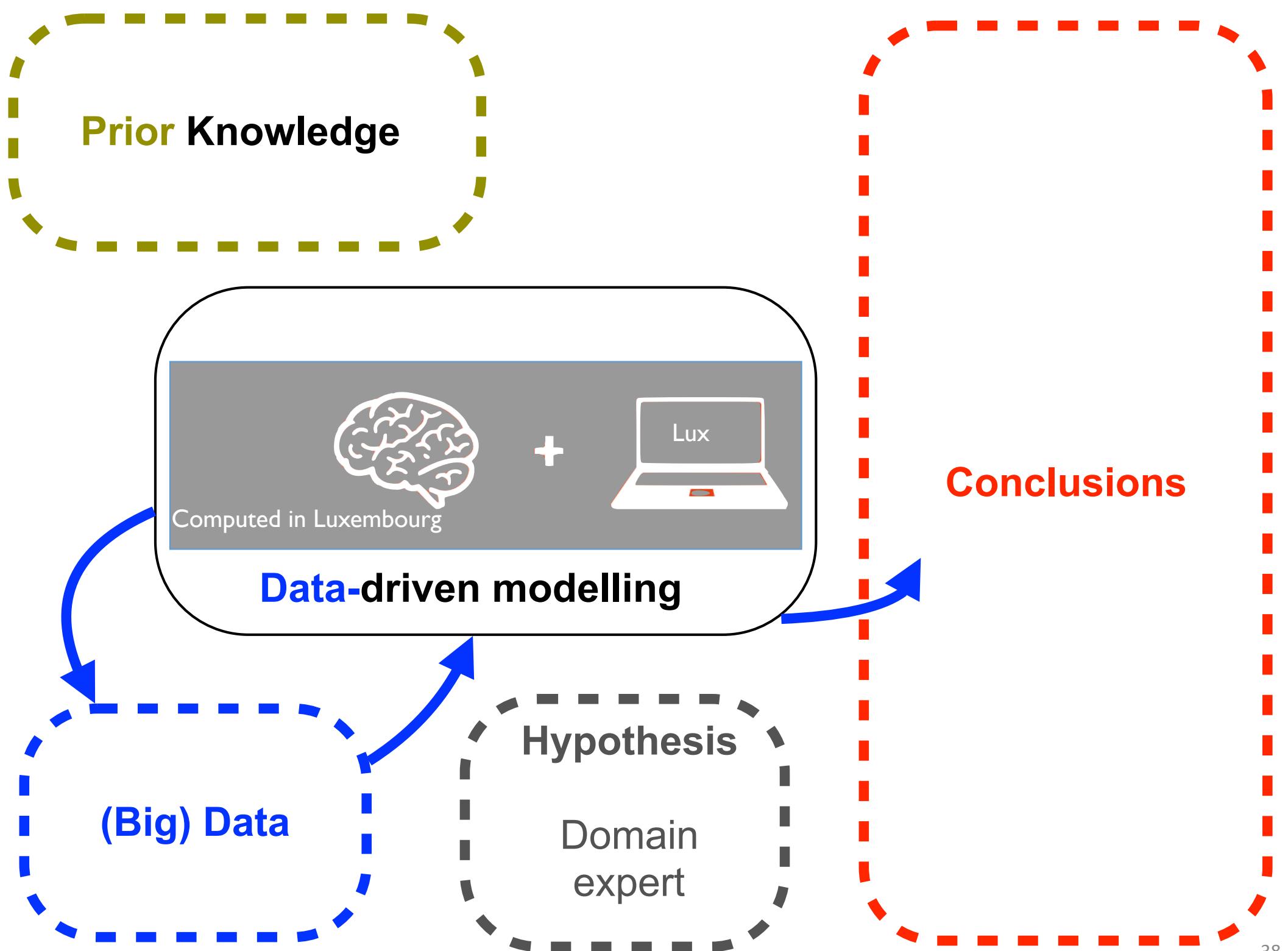


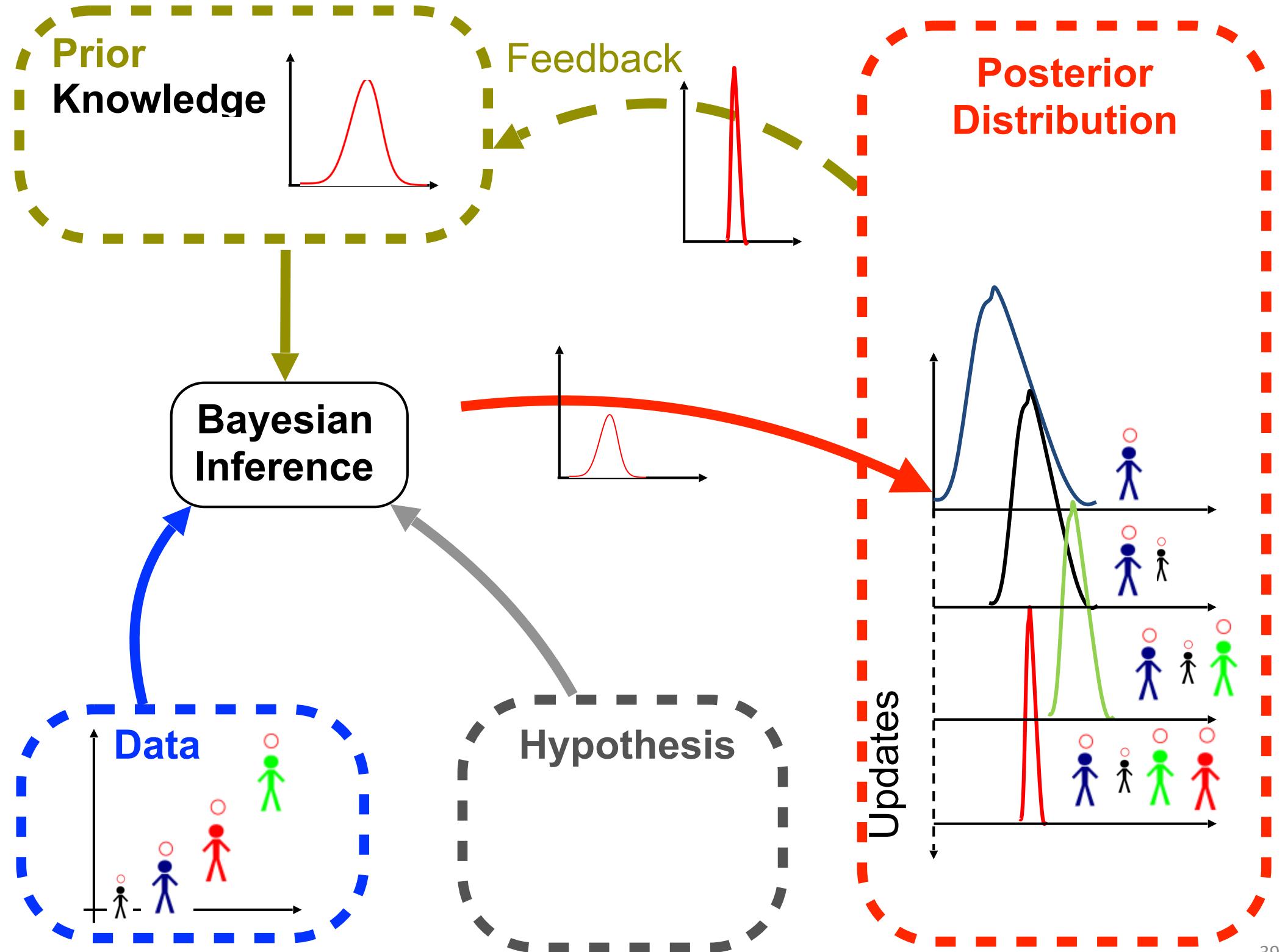
(Big) Data

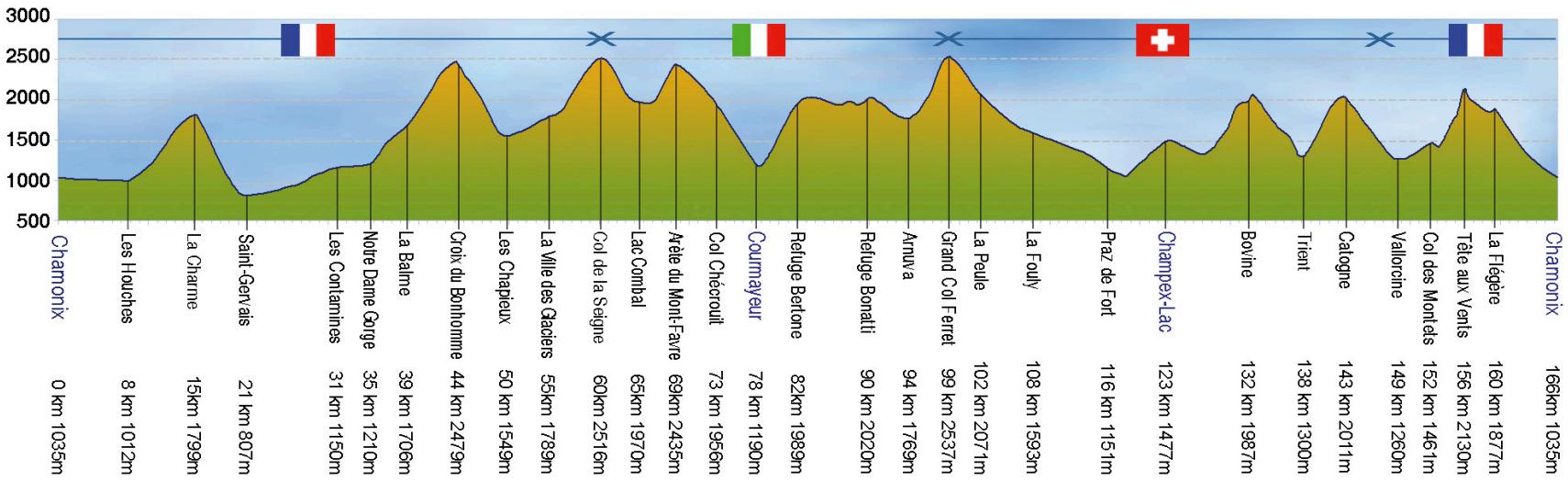
Hypothesis

Domain
expert





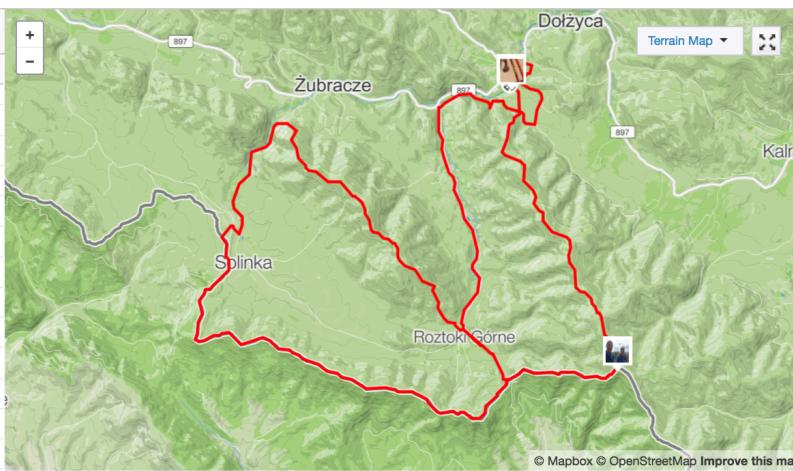




UTMB 177km running D+ 10,300m

Splits

KM	Pace	GAP	Elev
40	12:40 /km	6:59 /km	126 m
41	10:57 /km	7:00 /km	78 m
42	8:02 /km	6:29 /km	10 m
43	21:32 /km	11:59 /km	112 m
44	9:50 /km	7:12 /km	55 m
45	9:09 /km	7:54 /km	-56 m
46	9:44 /km	8:11 /km	-4 m
47	9:07 /km	8:17 /km	-36 m
48	8:30 /km	7:32 /km	-71 m
49	7:06 /km	6:26 /km	-94 m
50	7:45 /km	6:15 /km	-68 m
51	8:58 /km	7:11 /km	-211 m
0.6	9:17 /km	8:06 /km	-42 m



52km running D+ 2500m

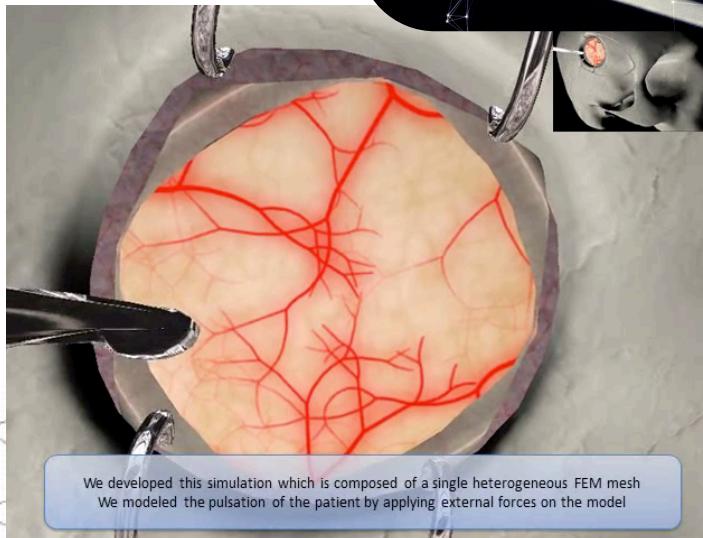


20km walking D+500m



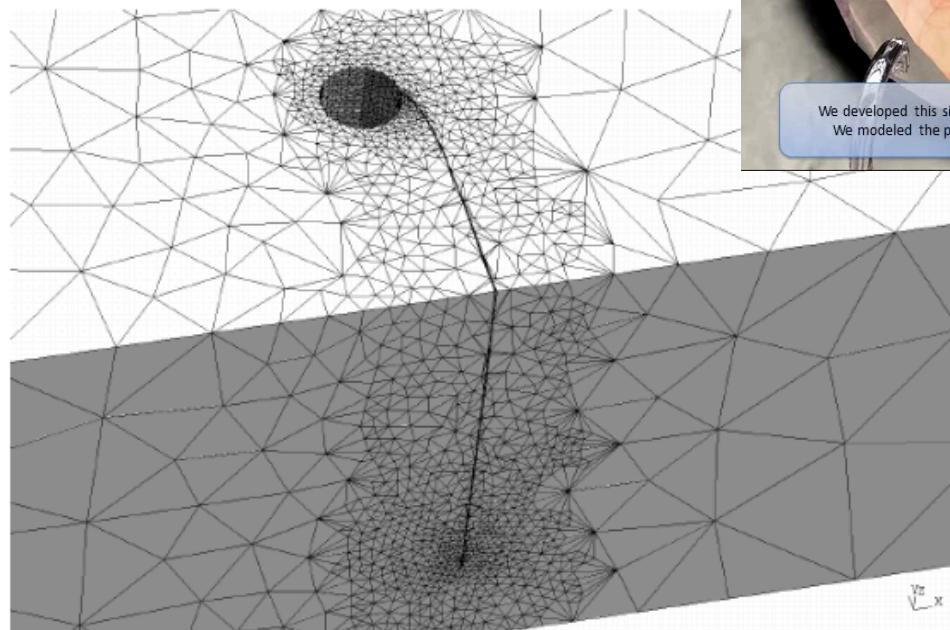
Alex Garland, *Ex Machina*, 2015

Personalised surgery
medicine

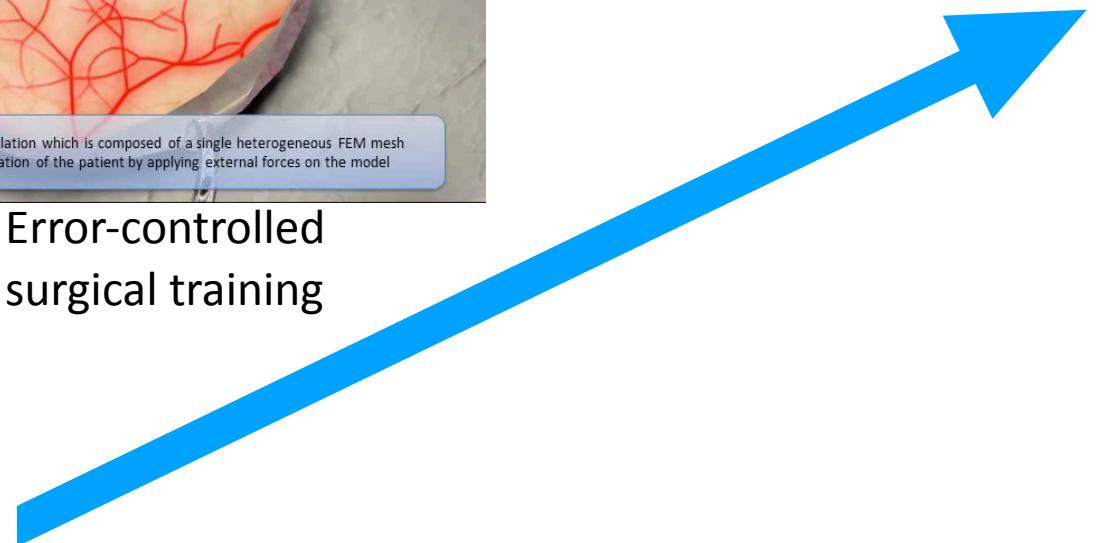


We developed this simulation which is composed of a single heterogeneous FEM mesh
We modeled the pulsation of the patient by applying external forces on the model

Error-controlled
surgical training

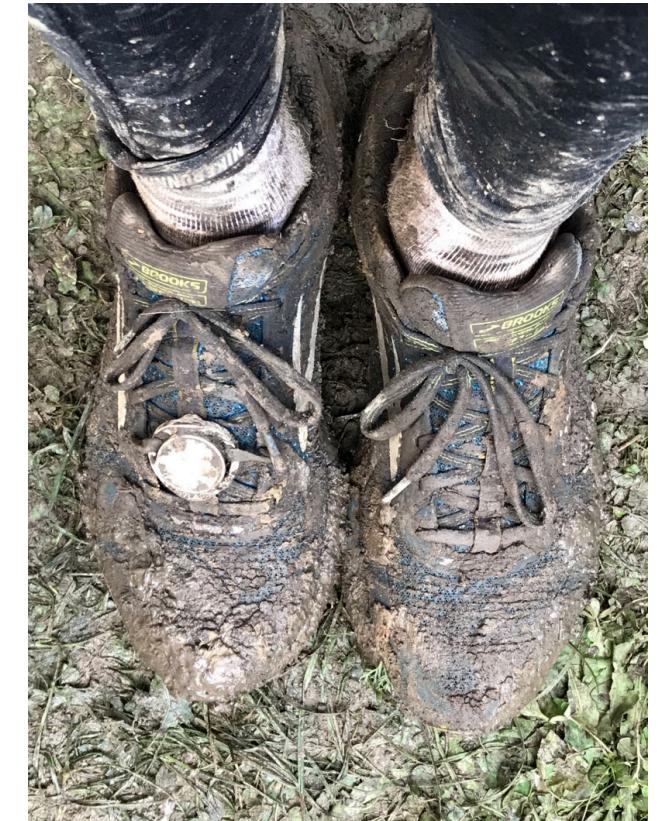


Error-controlled fracture mechanics



A bit of suffering...

$$\overbrace{\pi(\text{param.}|\text{obs.})}^{\text{Posterior}} = \frac{\overbrace{\pi(\text{param.}) \times \pi(\text{obs.}|\text{param.})}^{\text{Prior Likelihood}}}{\underbrace{\pi(\text{obs.})}_{\text{Evidence}}}$$



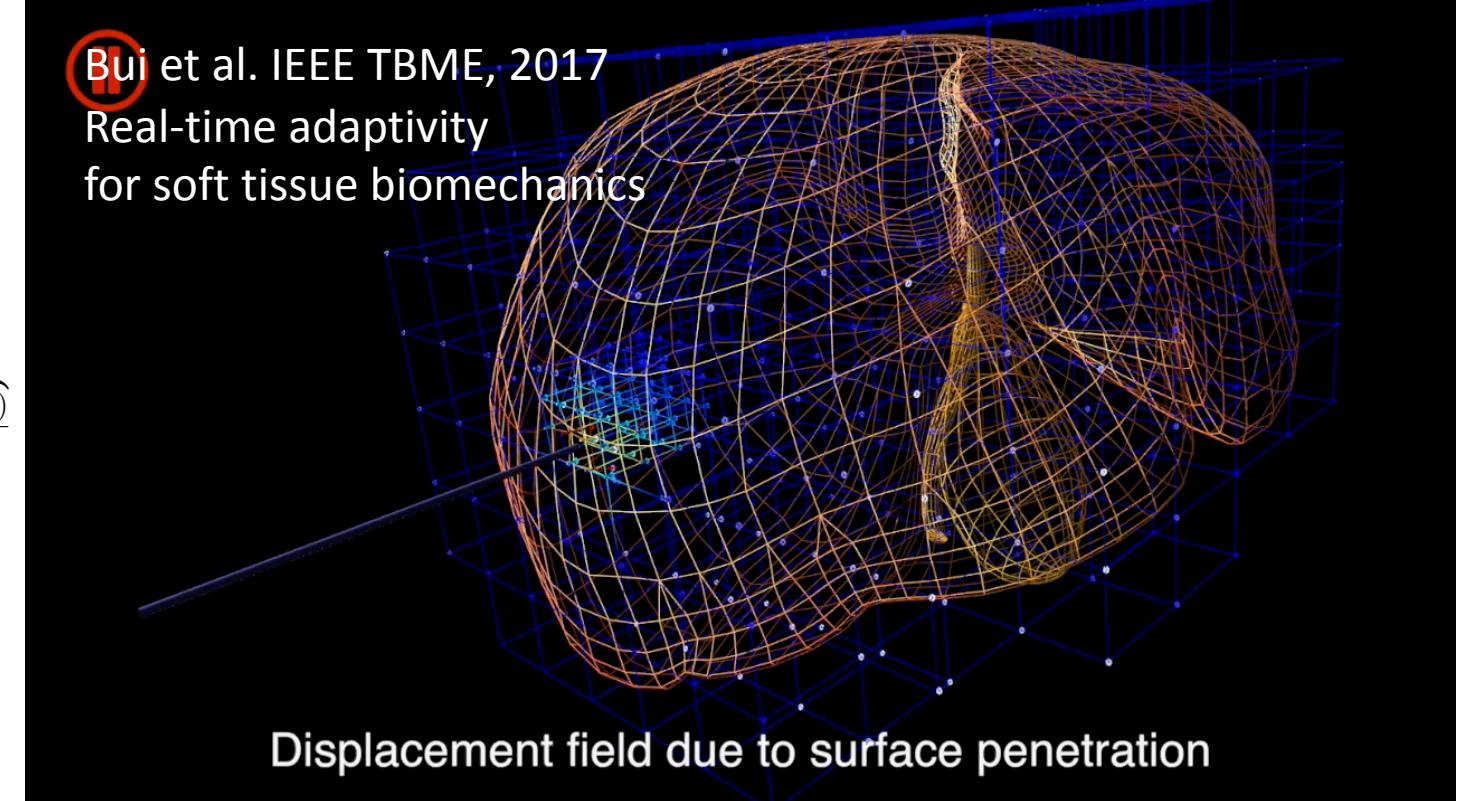
But much more fun!



Bui et al. IEEE TBME, 2017

Real-time adaptivity
for soft tissue biomechanics

$$\overbrace{\pi(\text{param.}|\text{obs.})}^{\text{Posterior}} = \frac{\overbrace{\pi(\text{param.}) \times \pi(\text{obs.}|\text{param.})}^{\text{Prior Likelihood}}}{\underbrace{\pi(\text{obs.})}_{\text{Evidence}}}$$



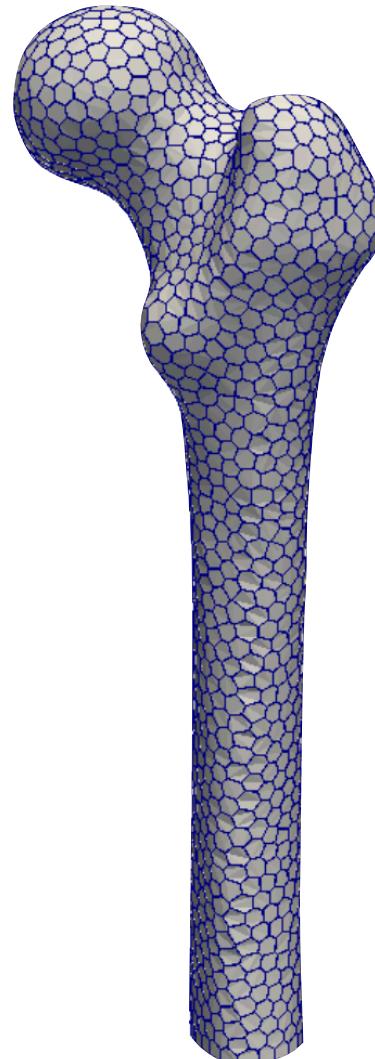
Thank you for your attention!



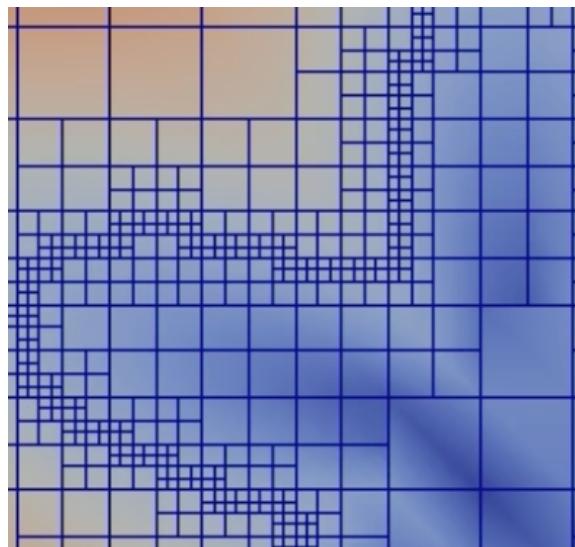
<http://legato-team.eu>



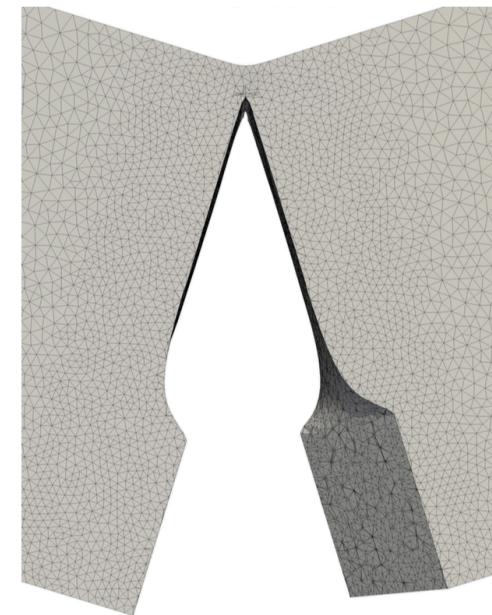
Finite Elements



polyhedral elements



unfitted FEM

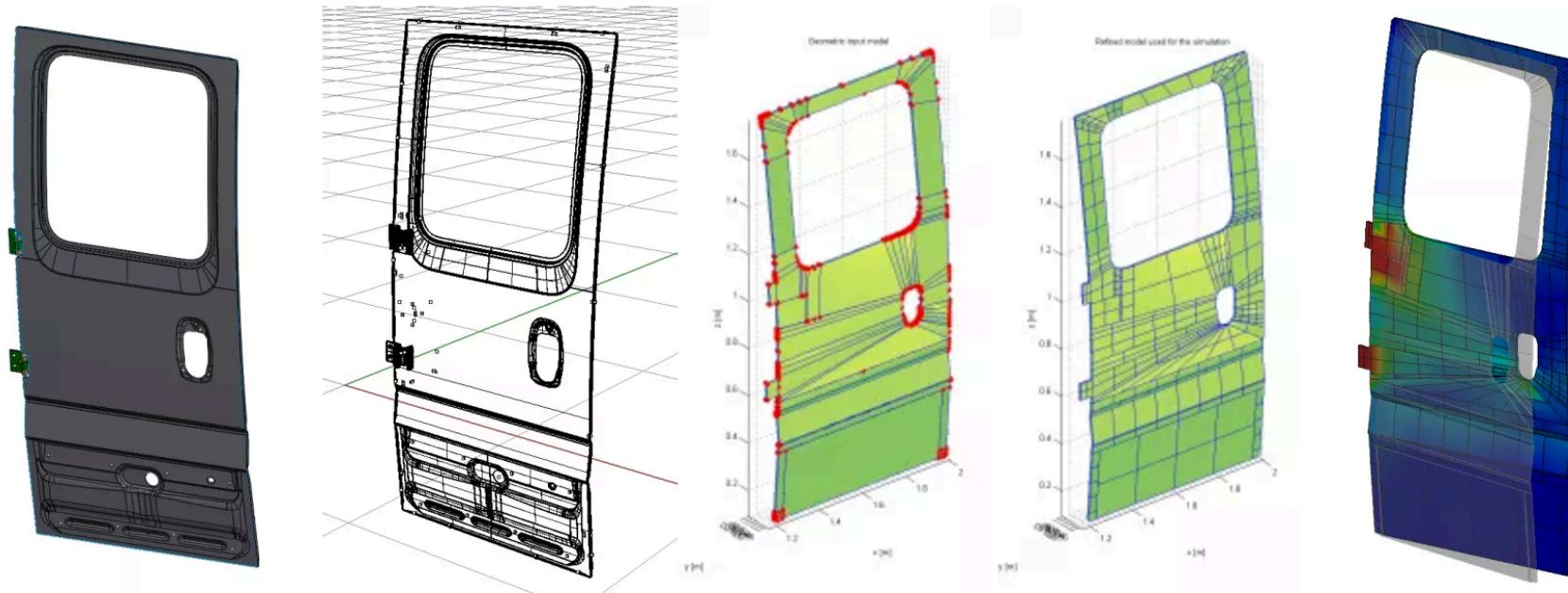


extended FEM



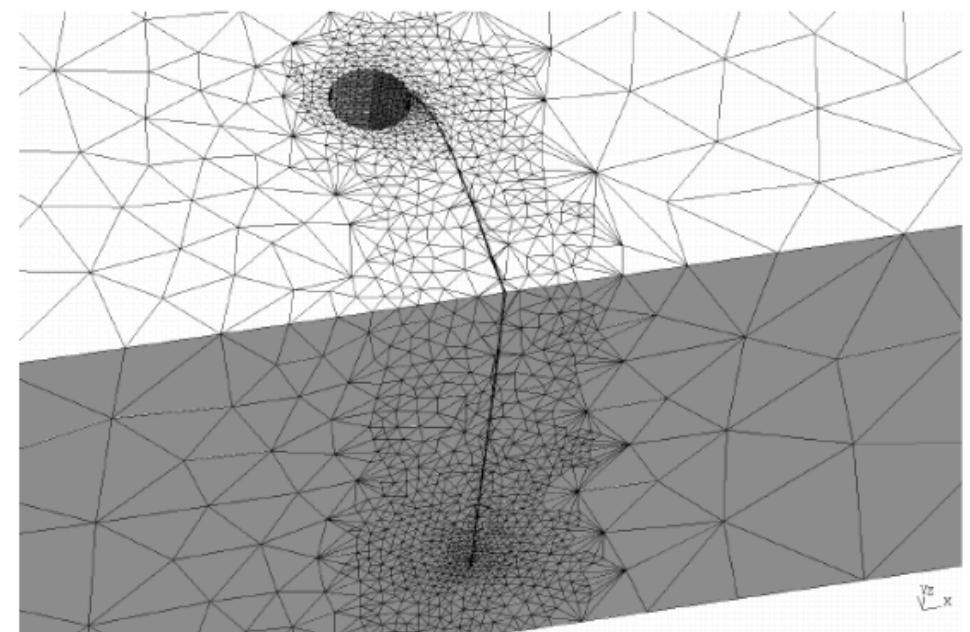
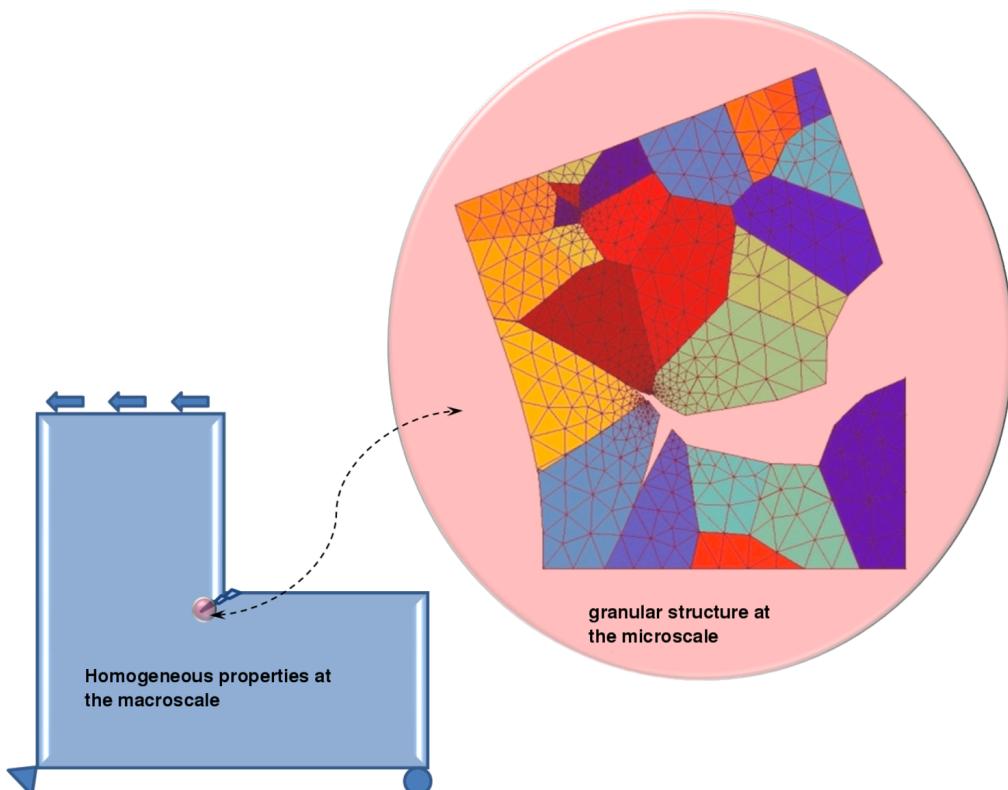
RealTCut

CAD-CAE integration



Geometry-Independent Field approximaTion - Isogeometric Analysis -Point collocation methods

Error estimation



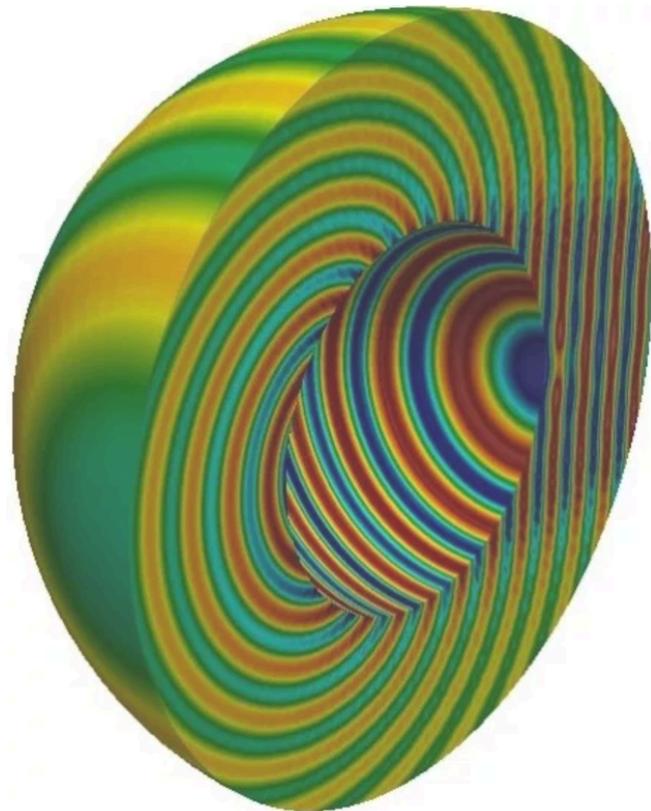
Most economical mesh



Coupled problems



Electromagnetics



Exterior acoustics

with Tahsin Khajaj U.T. Tyler

